

A FREQUENCY MODULATION MUSIC SYSTEM

BY

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THESIS

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## CHAPTER 1

### INTRODUCTION

This thesis describes the FMMS (Frequency Modulation Music System) which uses frequency modulation (FM) techniques to produce sounds which have dynamic frequency spectra. By using FM, a multitude of musical timbres can be produced. The system was designed and built in the ADSL (Advanced Digital Systems Laboratory) and integrates into the laboratory's Music System. This system is controlled by an 8085 CPU (Central Processing Unit) and interfaces to an organ keyboard, an amplifier and speakers, disk memory and several different music synthesizers. Figure 1.1 shows a block diagram representation of this arrangement.

The text is organized to first acquaint the reader with some of the theory behind FM and then goes on to present the considerations which were made in the actual designing of the system. Chapter two describes the mathematical theory behind frequency modulation, using spectral



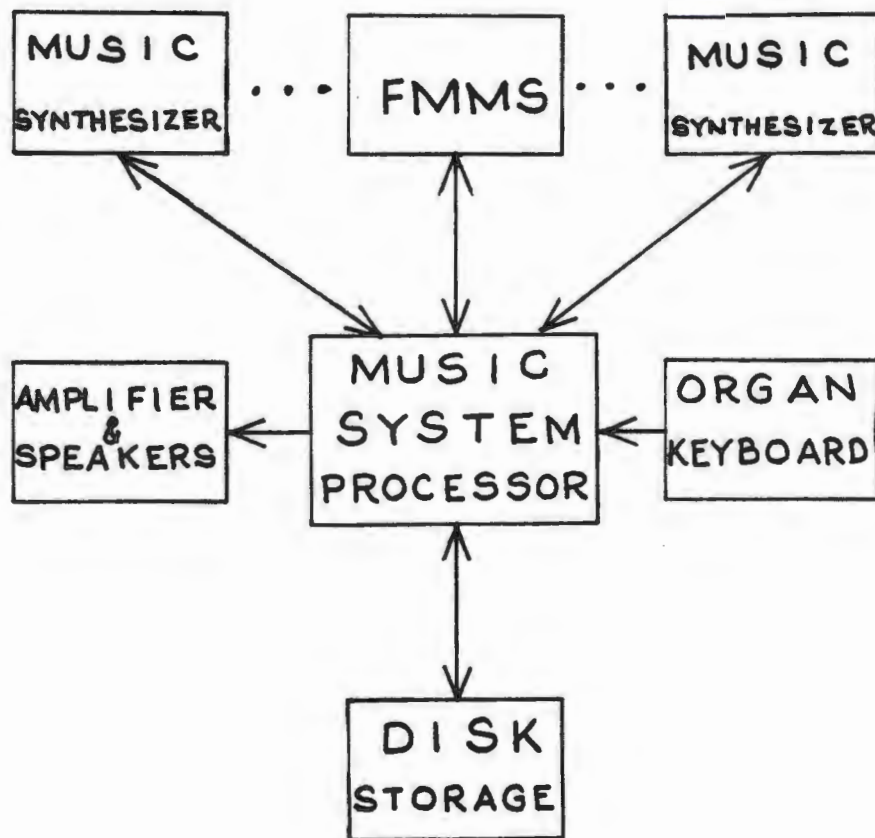


Figure 1.1 THE ADSL MUSIC SYSTEM

analysis to explain how a tone's timbre (sound character) can be enriched. Chapter three describes the hardware block structure of the FMMS, whereas chapter four goes into the details concerning the hardware design considerations. Chapter five is concerned with the system software, and in chapter six, some ideas are given on how to expand the FMMS to handle multivoice, followed by some concluding remarks.

### 1.1 Design Overview

The FMMS is chiefly an experimental project. The primary goal is to allow the user enough flexibility to create a variety of sounds presently unobtainable with the ADSL Music System.

The FMMS consists of four vector boards which are mounted in a rack in the ADSL Music System cabinet. The first three boards manipulate the data sent to them by the fourth board (the Processor Board). The hardware consists of pipeline registers and adders, a sine wave look-up table, a multiplier circuit and an output circuit consisting of a DAC (Digital-to-Analog Converter) and a low pass filter.

The data sent to the FMMS system hardware is controlled by an 8085 CPU. The CPU basically waits for interrupts from the keyboard port. When it senses that a key has been pressed or released, it sends out the appropriate data at the proper times to each of five generator registers.

## 1.2 Brief Historical Background

FM synthesis of music is a technique which is only about ten years old. Synthesizing music by electronic means dates back to the early 1900's with the development of Thaddeus Cahill's Telharmonium. This was a huge machine which was driven by alternators. In 1920, the Theremin was introduced by USSR's Leon Theremin. It was an antennae synthesizer which used the capacitance from one's hand to alter the beat frequency from dual oscillators. The first electronic music studios were introduced in the early 1950's.

With the development of the computer, new ways of synthesizing music seemed limitless. Max Mathews of Bell Labs was the first to use digital computers to produce music back in 1960. By the early 1970's, John Chowning demonstrated the effectiveness of frequency modulation techniques in simulating "natural instrument tones." The late 1970's marked the advent of fabricating music synthesizers on a single integrated circuit chip [1].

Presently, three means of synthesizing music are in vogue. Additive synthesis, which generates a sine wave for each harmonic and adds them all together. Non-linear synthesis, which "processes" an input sine wave into various harmonic frequencies. The processor essentially transforms the input into a power series expansion whose coefficients depend on the input amplitude [1]. Finally, FM, which controls the

evolution of the spectrum rather than controlling each individual frequency component.

## CHAPTER 2

### THEORETICAL CONCEPTS

#### 2.1 Static Spectra

Many attempts have been made at producing tones with interesting timbres. Musical Engineers have tried using combinations of triangle, square, sine and sawtooth waveforms in an effort to simulate a timbre with more life and zest than the usual electronic sounding synthesizers which use square or sine waves exclusively. The problem with these attempts is that regardless of how one combines these various waveforms, the spectrum it produces will be static. For example, let us say one wants to produce an interesting tone with a fundamental frequency of 100Hz. By using a sine wave, the spectrum simply includes the fundamental at 100Hz as shown in Figure 2.1. Although simple, this tone lacks character. Next, one could use a square wave, producing the spectrum diagrammed in Figure 2.2. Square waves sound nasally and

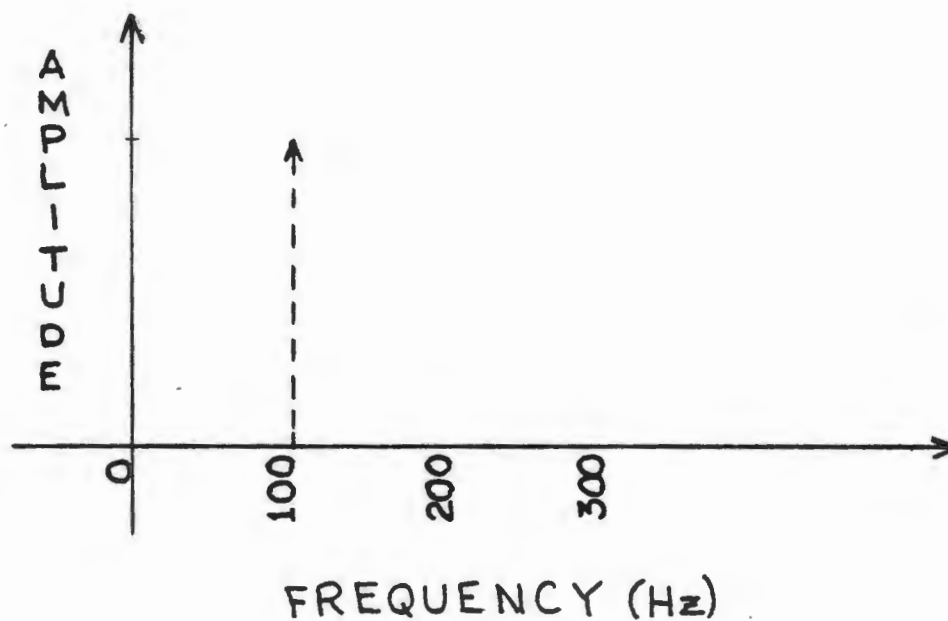


Figure 2.1 SINE WAVE SPECTRUM

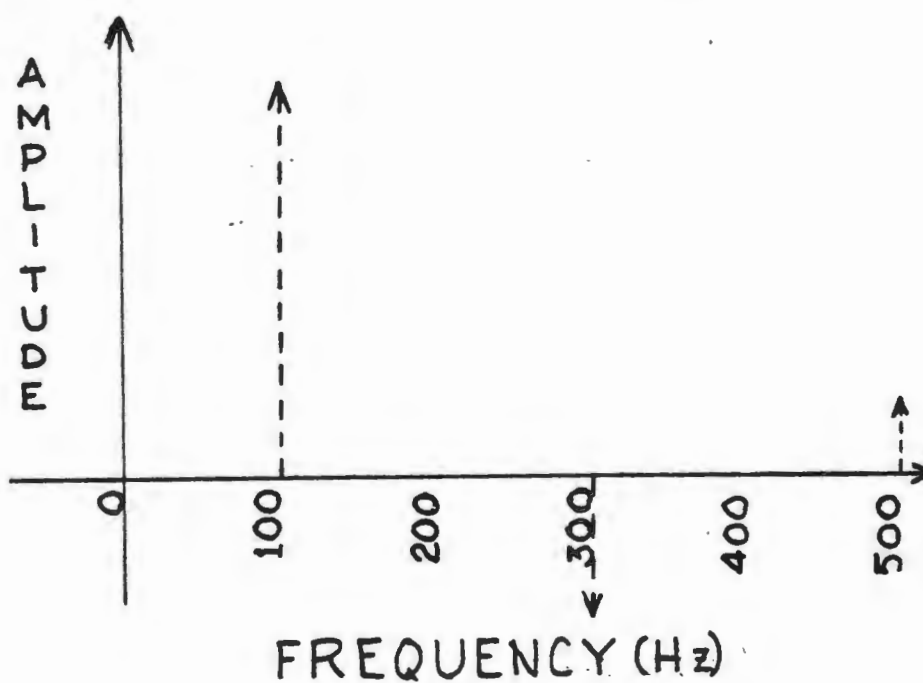


Figure 2.2 SQUARE WAVE SPECTRUM

somewhat piercing. In Figure 2.3, the previous spectrum is added to that of a sawtooth wave (with fundamental frequency of 100Hz).

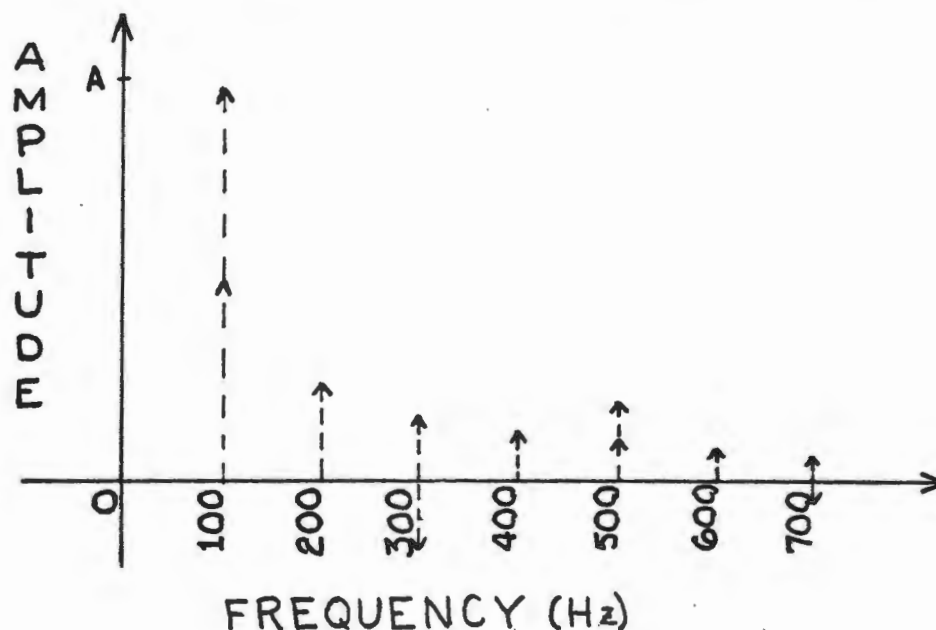


Figure 2.3 SPECTRUM OF SAWTOOTH AND SQUARE WAVE COMBINATION

By adding these components vectorially one notices that every other odd harmonic has been eliminated. This spectrum is becoming broader (amplitudes of harmonics are increasing). This tends to add more brightness or color to the tone.

The purpose of the previous illustrations is to give the reader some idea of what is meant by a broad spectrum and how a note's timbre can be enriched by broadening the spectrum.

Notice that in the last two illustrations, although the spectrum is complex, the amplitudes of all the frequency components remain constant throughout the duration of the note. It is for this reason that these techniques have failed in any attempts to simulate common musical instruments (e.g. brass, woodwinds, percussion etc.), the ultimate test of a music system's capabilities [2].

## 2.2 Dynamic Spectra

The FM equation allows dynamic control of the spectrum by varying a parameter called the modulation index. If the timbre of common instrument tones depended upon the relative magnitudes of each frequency component, the FM approach would probably be ineffective. However, the results achieved by John Chowning and others have shown that the timbre is more dependent on the evolution of the spectrum as a whole rather than the evolution of individual components [3].

### 2.2.1 Mathematical description

To see how a dynamic spectrum is realized using linear frequency modulation, the general FM equation will first be derived. To produce an FM signal, one superimposes an AC waveform on a DC waveform and uses this signal to control a variable oscillator whose instantaneous output frequency is proportional to the input signal. Thus:



$$\begin{aligned}
 f_{\text{inst}} &= K S_{\text{d.c.}} + K S_{\text{a.c.}} \\
 &= f_c + f_d \cos(2\pi f_m t)
 \end{aligned}
 \tag{1}$$

where the modulating frequency,  $f_m$ , is the frequency of the AC signal. The carrier frequency,  $f_c$ , is proportional to the DC signal, and  $f_d$  is the maximum amount by which the output frequency deviates from the carrier frequency. The output signal could be thought of as the vertical projection of a vector rotating on the unit circle as illustrated in Figure 2.4. The function  $A(t)$  is the instantaneous phase of the vector  $S(t)$ . Since the time derivative of the phase is the instantaneous frequency, an expression for the instantaneous phase can be obtained by integrating equation (1):

$$\begin{aligned}
 A(t) &= 2\pi \int_0^t [f_c + f_d \cos(2\pi f_m t')] dt' \\
 &= 2\pi f_c t + (f_d/f_m) \sin(2\pi f_m t)
 \end{aligned}
 \tag{2}$$

Therefore the output signal  $S(t)$  is:

$$S(t) = \sin [2\pi f_c t + (f_d/f_m) \sin(2\pi f_m t)] \tag{3}$$

The coefficient  $f_d/f_m$  is known as the modulation index ( $M$ ). Equation (1) can now be rewritten in the following form:

$$f(n) = f_c + (M f_d) \cos(2\pi f_m nT) \tag{4}$$

Where equation (1) has been changed from a continuous to a discrete frequency whose sampling period is denoted by  $T$ . The output signal, therefore, can be completely specified by the three parameters:  $f_c$ ,  $f_m$  and  $M$ .

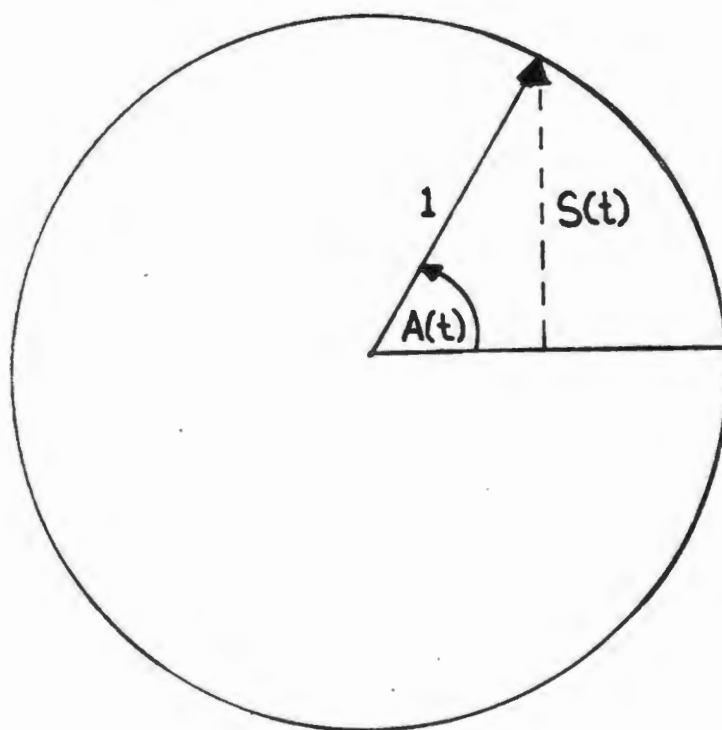


Figure 2.4 ROTATING VECTOR REPRESENTATION OF FM SIGNAL

Now by referring back to equation (3) we can begin our realization of the dynamic spectral behavior that is characteristic of frequency modulation.

Using a trigonometric identity:

$$\begin{aligned} S(t) = & \sin(2\pi f_c t) \cos[M \sin(2\pi f_m t)] \\ & + \cos(2\pi f_c t) \sin[M \sin(2\pi f_m t)] \end{aligned} \quad (5)$$

In order to simplify this expression still further one needs to utilize the "Bessel Functions" which define the sine of a sine and cosine of a sine in terms of Bessel polynomials. The identities are:

$$\sin[M \sin(x)] = 2[J_1(M)\sin(x) + J_3(M)\sin(3x) + \dots] \quad (6)$$

$$\cos[M \sin(x)] = J_0(M) + 2[J_2(M)\cos(2x) + J_4(M)\cos(4x) + \dots] \quad (7)$$

Thus:

$$\begin{aligned} S(t) = & \sin(2\pi f_c t) J_0(M) + 2[J_2(M)\cos(4\pi f_m t) + \dots] \\ & + \cos(2\pi f_c t) 2[J_1(M)\sin(2\pi f_m t) + J_3(M)\sin(6\pi f_m t) + \dots] \end{aligned} \quad (8)$$

Again using trigonometric identities:

$$\begin{aligned} S(t) = & J_0(M) \sin(2\pi f_c t) \\ & + J_1(M) \sin[2\pi(f_c + f_m)t] - \sin[2\pi(f_c - f_m)t] \\ & + J_2(M) \sin[2\pi(f_c + 2f_m)t] + \sin[2\pi(f_c - 2f_m)t] \\ & + J_3(M) \sin[2\pi(f_c + 3f_m)t] - \sin[2\pi(f_c - 3f_m)t] \end{aligned} \quad (9)$$

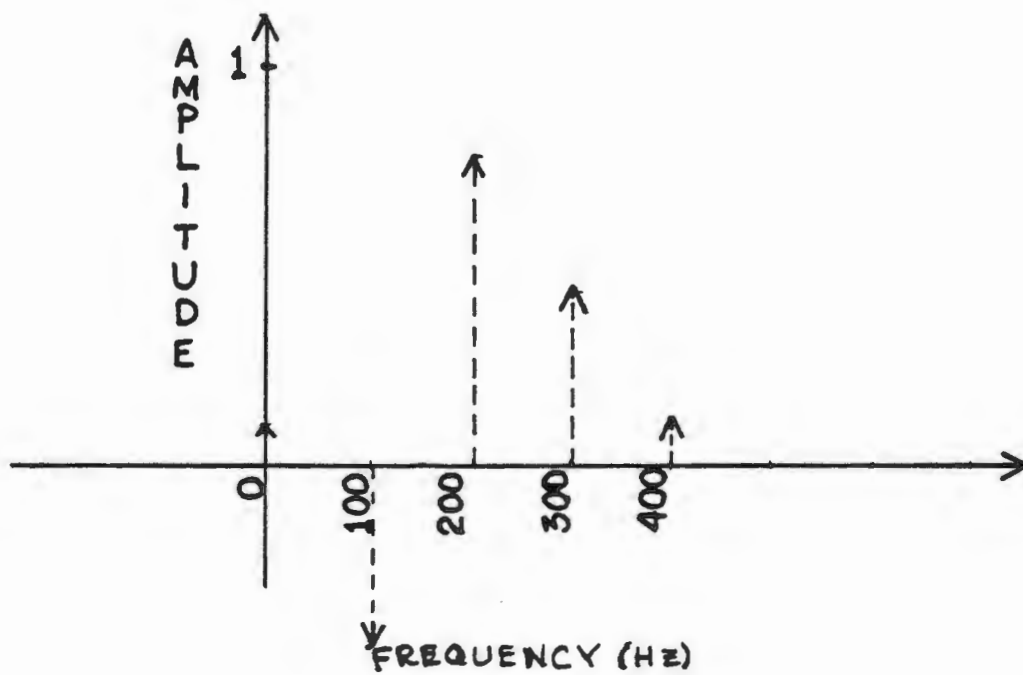
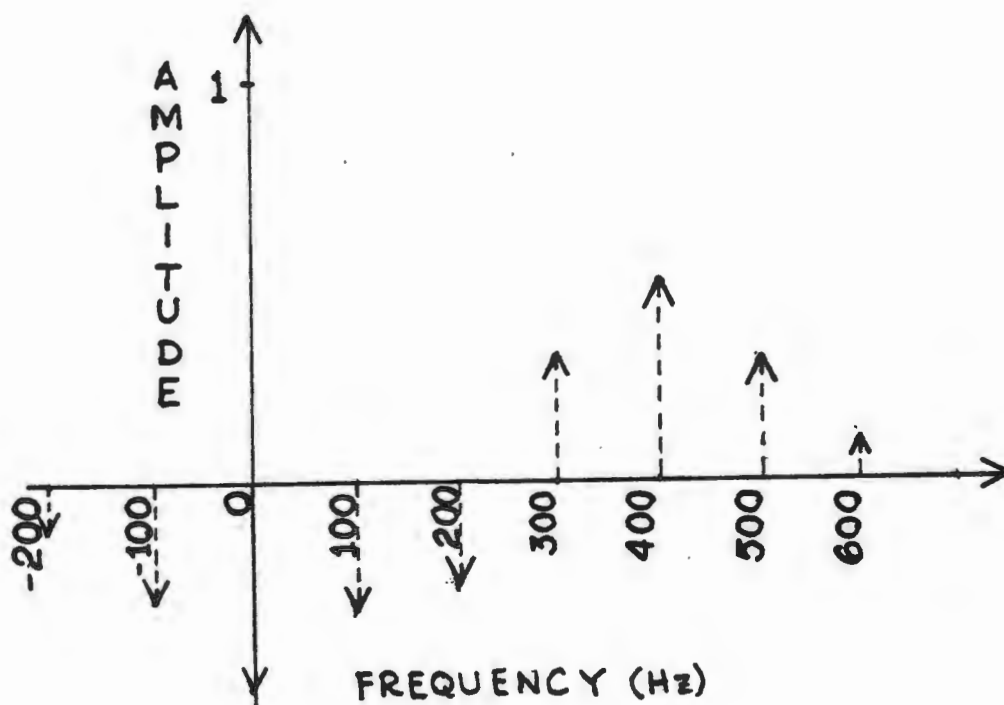
### 2.2.2 Example

Now to illustrate spectral evolution let us take an example. Suppose  $f_c = 200\text{Hz}$ ,  $f_m = 100\text{Hz}$  and  $f_d = 100\text{Hz}$  ( $M=1$ ). The Bessel Function values for  $M=1$  are:  $J_0 = .77$ ;  $J_1 = .44$ ;  $J_2 = .11$ ;  $J_3 = .02$ . This will produce the spectrum illustrated in Figure 2.5. If the amount of frequency deviation is increased from 100Hz to 300Hz ( $M=3$ ), the result shown in Figure 2.6 is obtained.

Since  $\sin(-x) = -\sin(x)$ , the negative frequency components get reflected and add vectorially to the positive frequency components. One will notice, however, that the spectrum has "spread out" yielding higher frequency components of significant weight. Essentially, some of the energy from the carrier signal has been distributed to the other higher and lower frequency components. This, finally, is what is meant by spectrum evolution. As the spectrum continues to broaden, the timbre of the note gets richer and more interesting [4].

One can control this dynamic action of the spectrum by simply applying a time envelope on the modulation index parameter. This technique is used in the FMMS. In addition, the FMMS has another time envelope which is applied to the amplitude of the output wave yielding this final FM equation:

$$S(nt) = A(nt) \sin [2\pi f_c nt + M(nt) \sin (2\pi f_m nt)] \quad (10)$$

Figure 2.5 FM SPECTRUM ( $M=1$ )Figure 2.6 FM SPECTRUM ( $M=3$ )

Each instrument, therefore, will have three controlling parameters:  $A(nT)$ , the output amplitude envelope function;  $M(nT)$ , the modulation index envelope function and  $(f_c/f_m)$ , the ratio of the carrier frequency to the modulating frequency. If one represents this ratio in the form of  $N_1/N_2$ , where  $N_1$  and  $N_2$  have all common factors divided out, then the fundamental frequency of the modulated carrier will be:

$$f_o = f_c / N_1 = f_m / N_2 \quad (11)$$

By making the ratio of  $f_c$  to  $f_m$  a small integer, a harmonic spectrum results (as can be seen in the example). However, if this ratio is non-integral, an inharmonic spectrum results, which should be useful in simulating percussive sounds.

## CHAPTER 3

### SYSTEM DESIGN

This and the next chapter deal with the hardware design of the FMMS. This chapter describes each subsystem in block diagram form and then puts the units together to give the reader a view of the overall system. Most of the specifics in the design are presented in chapter four.

In order to realize equation (10) as a digital hardware system, one needs to have a modulating frequency generator, a carrier frequency generator, a multiplier, an amplitude and modulation index envelope generators and a DAC.



### 3.1 Frequency Generators

The frequency generators are essentially phase angle generators. The idea is to load a register with a value (phase angle increment) which is proportional to the frequency one wants generated. This value gets periodically added into an accumulator register whose output is used to address a sine wave table. When the accumulator overflows, a new cycle of the sine wave begins. Thus, the number of times the accumulator overflows per second, will be the frequency of the output sine wave. Loading the increment register with a larger value will cause the accumulator to overflow more often and thus increase the frequency of the output wave. This scheme is illustrated in Figure 3.1.

The output frequency is dependent on the phase angle increment (I), the sampling rate (S), and the sine table length (L), by the following equation:

$$f = I \times (S/L) \quad (12)$$

These three values (I, S and L) depend on how elaborate a system one wants. The considerations made in determining them can be found in the next chapter. In order to increase the utilization of the sine wave table, the ROM (Read Only Memory) address was multiplexed between the modulating phase angle and the modulated carrier phase angle.



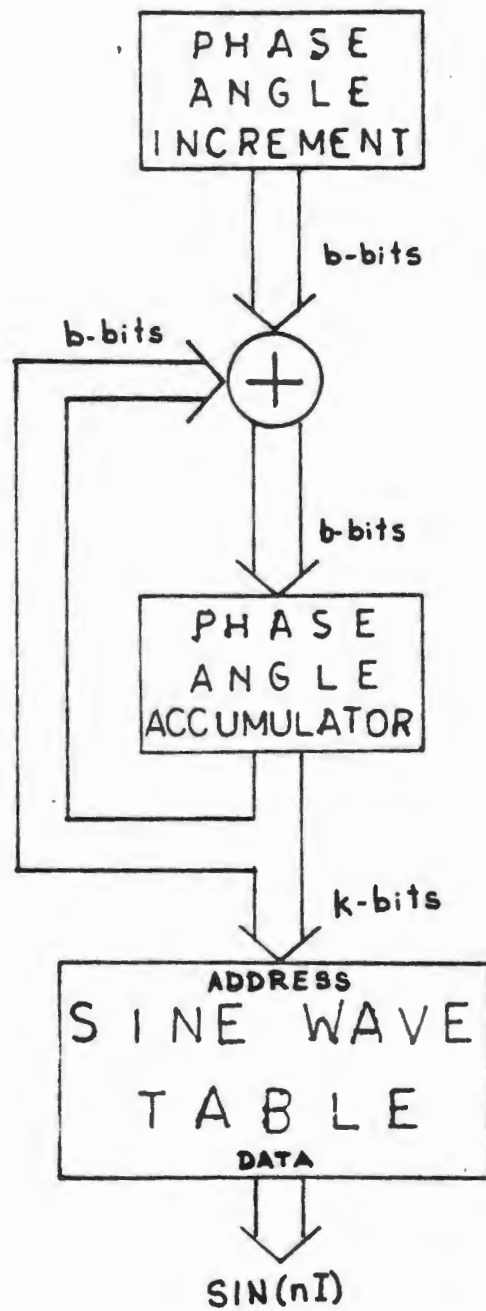


Figure 3.1 FREQUENCY GENERATOR BLOCK DIAGRAM

### 3.2 Envelope Generators

The envelopes generated by the FMMS are concatenated linear segments whose slopes, which are preprogrammed, are loaded into a slope increment register. Like the frequency generators, this increment gets added periodically into an accumulator register. Unlike the frequency generators, however, where overflow starts a new cycle of the waveform, the envelope accumulator overflow simply increments or decrements a ramp register. Figure 3.2 illustrates this process. This design technique was used to shorten the register lengths which would need to be twice as large if the technique illustrated in Figure 3.1 were used.

Once again, the value loaded into the slope increment register depends on the sampling frequency and its value should be adjusted so that it never causes overflow in the ramp register. For the duration of the note, the CPU is responsible for updating the slope increment register to alter the slope of the ramp.  $M(nT)$  and  $A(nT)$  are generated in this part of the system.

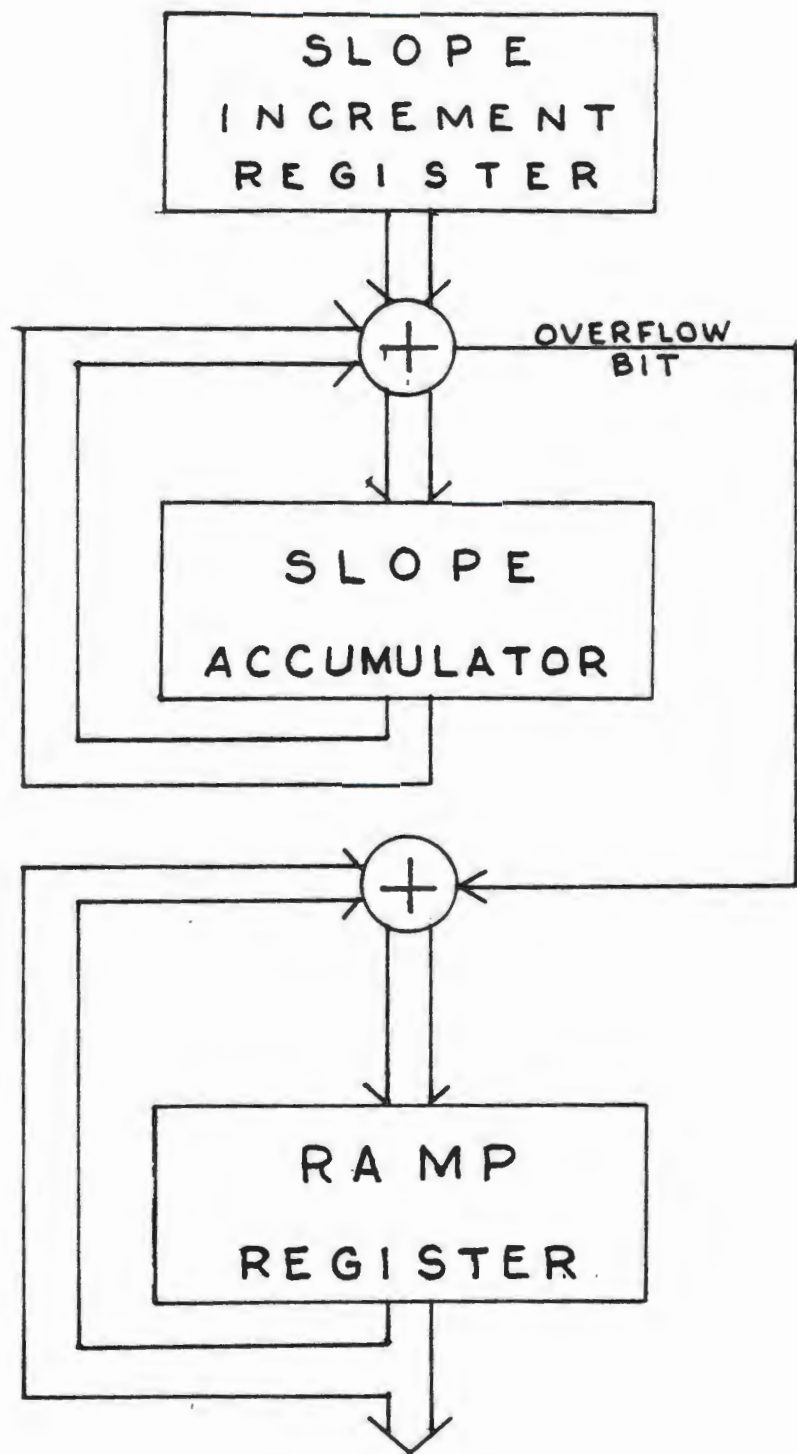


Figure 3.2 ENVELOPE GENERATOR BLOCK DIAGRAM

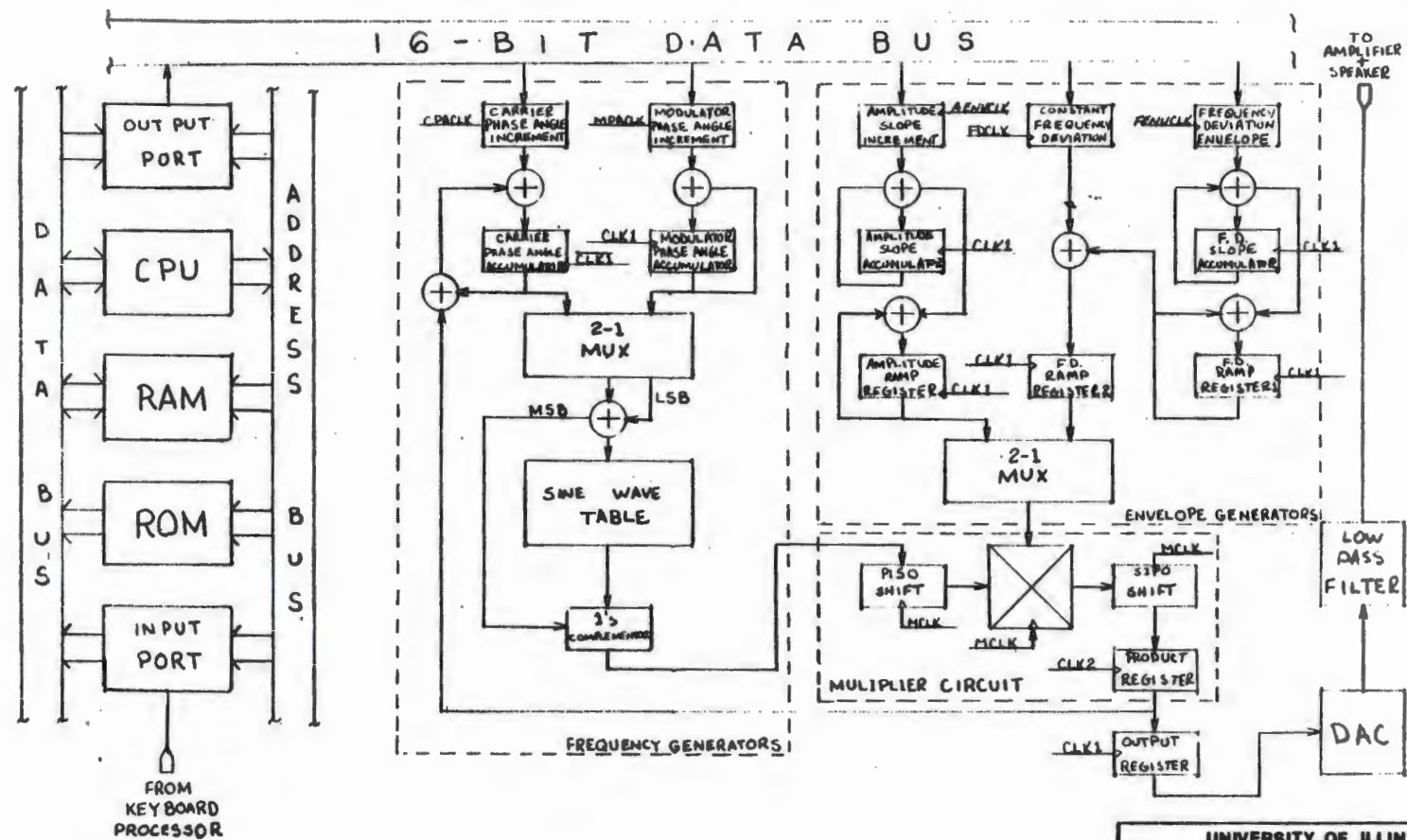
### 3.3 Multiplier Circuit

In order to provide for the dynamic spectrum, the modulating frequency needs to be multiplied by a varying modulation index  $M(nT)$  (provided by the envelope generator subsystem). In addition, the modulated carrier wave is multiplied by  $A(nT)$  to provide for a dynamic output amplitude. These two functions were multiplexed into the multiplier input of a multiplier, and the output of the sine wave generator was used as the multiplicand. As one can begin to discern, the timing is very critical. Refer to the timing diagram in APPENDIX B for the complete details on the timing of the pipeline.

### 3.4 Digital-to Analog Conversion

Once each sample has been through the pipeline twice (once in forming the instantaneous modulation frequency and the second time forming the instantaneous modulated carrier frequency), it is sent to the output register which converts this digital data into an analog voltage. Then, after going through a low pass filter, it is sent out to the Music System amplifier and speaker. A 16-bit DAC would produce very low distortion, however it would cost hundreds of dollars. Therefore a 12-bit DAC was used, which for the FMMS is quite adequate.

Figure 3.3 shows a block diagram of the entire FMMS. In the next chapter, specifics concerning register length, sampling frequency, type of multiplier and sine wave table length are discussed.



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FMMS SYSTEM			
BLOCK DIAGRAM			
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DRAWN BY	R. M. KAMINSKY	No.	1/1
REV.	DESCRIPTION	DATE	MADE BY CHK'D BY

Figure 3.3 FMMS BLOCK DIAGRAM

## CHAPTER 4

### HARDWARE DESIGN

The previous chapter illustrated the general hardware structure of the FMMS. This chapter describes the various considerations which were made in completing the design of the hardware.

#### 4.1 Register Length

The first concern was how large to make the pipeline registers in the frequency generator and envelope generator circuits.

#### 4.1.1 Frequency generator circuit

For the frequency generators, the register length depends on the maximum and minimum frequencies one would like to generate. Since the FMS is to interface with the organ keyboard, the maximum allowable frequency should be  $2^{13}$ -1Hz. An additional sign bit is needed since frequency modulation requires negative as well as positive frequencies.

To determine the minimum frequency, one must weigh cost as well as resolution. The most noticeable "frequency jitter" will be heard in the lower frequencies. Generally, comparisons are done around note  $C_2 = 65.4\text{Hz}$ . The unit of measure is the cent (one cent =  $1/1200$  of an octave). Therefore:

$$1 \text{ cent} = 2^{1/1200} \quad (13)$$

To form a basis for comparison, some of the most elaborate systems have a frequency resolution of one cent at  $65.4\text{Hz}$ . Expensive tape recorders have wow and flutter figures around 0.1% or lower. At  $65.4\text{Hz}$ , this would be equivalent to 1.73 cents. In Table 4.1, cent deviation comparisons are made for registers having 14, 16 and 18 bits.



Table 4.1 ACCURACIES OF VARIOUS REGISTER LENGTHS

# of bits	f(min)	f(max)	cents dev. around 65.4Hz
14	1.0000	8191	26.30
16	0.2500	8191	6.60
18	0.0625	8191	1.65

Obviously, with 18-bit registers, one would be able to produce the kind of accuracy available on some of the most expensive systems. However to do this would require an 8-bit microprocessor to do triple precision arithmetic. Microprocessors are relatively slow at performing data manipulation in music synthesis applications, so this slowdown would be more detrimental than would the loss of accuracy in using a smaller register length. For this reason the FMMS uses 16-bit pipeline registers in the frequency generator circuit.

#### 4.1.2 Envelope generator circuit

The decision on how large to make the envelope generator registers depends on how much noise can be tolerated after the multiplier circuit. Figure 4.1 illustrates the model used in evaluating the SNR (Signal-to-Noise Ratio) for the signal coming out of the multiplier.

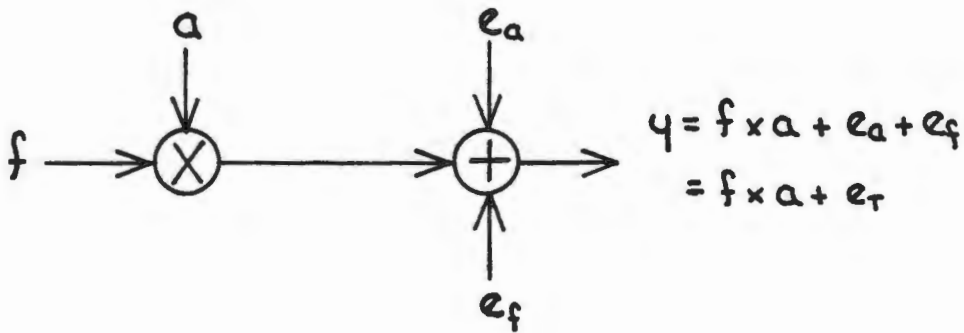


Figure 4.1 MODEL OF MULTIPLIER QUANTIZATION NOISE

The errors are due to truncation of the frequency and amplitude signals. For this calculation, the two input signals are considered to be fractions, therefore the error will be equivalent to the weight of the least significant bit position. As an example, consider  $f$  &  $a$  to be 8 bits each (including sign), then:

$$e_a + e_f = 2^{-7} + 2^{-7} = 2^{-6} = e_T \quad (14)$$

$$\text{SNR} = 10 \log (1/e_T^2) = 36.12\text{dB}$$

where the variance of the signal is normalized to 1. Table 4.2 lists the SNR's for several amplitude and frequency register lengths.

Table 4.2 MULTIPLIER OUTPUT SNR FOR VARIOUS INPUT REGISTER LENGTHS

f (bits)	a (bits)	SNR (dB)
-----		
12	8	41.62
12	12	60.21
12	16	65.70
16	8	42.11
16	12	65.70
16	12	65.70
12	INFINITE	66.23
16	INFINITE	90.31

The 8-bit register values appear rather poor. A SNR around 60dB would be much better. For this reason, 12-bit registers are used in the envelope generator circuit.

#### 4.2 Pipeline Clock

The next concern was the frequency at which to sample the data. By having the pipeline clock be a power of 2, the frequency increment values would be equal to the actual frequency desired, but shifted right or left. Clock frequency values of  $2^{14}$  or  $2^{15}$  were possibilities. By making it much higher, one decreases the throughput of the pipeline. To be able to completely recreate the original waveform, the sampling frequency should be at least 2 1/2 times the highest frequency component. This requirement is not met using a clock frequency of  $2^{14}$ Hz since the highest fundamental frequency is  $2^{13}$ Hz. Therefore,  $f_{\text{clk}} = 2^{15}$ Hz in the FMMS.

#### 4.3 Sine Wave Table

A sine wave table stored in ROM is probably the easiest way to convert an instantaneous phase into the sine function. Again, a decision must be made as to how long the table should be and how many bits each word in the table should have.

In order to properly evaluate what size table should be used, reference was made to an article written by Richard Moore entitled "Table Lookup Noise for Sinusoidal Digital Oscillators" [5]. In the article, Moore compares the worst-case  $SN_eR$  (signal-to-error noise ratio) of various size tables using three methods of addressing the table: truncation, rounding and interpolation.

A study conducted at the Center for Computer Research in Music and Acoustics at Stanford University concluded that a 4096-word x 12-bit/word table would produce very negligible distortion [6]. This table, however, contained 360 degrees of the sine wave and truncated the lower address bits. Moore's tables contain only 180 degrees of the sine wave and therefore use the most significant address bit to determine the polarity of the sine wave. Thus, the table size mentioned above would be equivalent to a 2048-word x 11-bit/word table which Moore lists as having a  $SN_eR$  of 54.4dB. The ADSL has an abundance of 2K x 8 EPROM's (Eraseable-Programmable Read Only Memory) (2716) so two of these chips were used to build a 2K x 15-bit sine wave table. If truncation were used, this would yield a  $SN_eR$  of 54.4dB (according to the article, adding more than  $b$  bits, where  $2^b$  = memory length, does not improve the  $SN_eR$  since then practically all the noise is due to the finite table length). By adding just three more adder chips a round-off adder was inserted, thus improving the  $SN_eR$  to 60.4dB.

#### 4.4 Multiplier Circuit

The multiplier circuit, which is the bottleneck of the pipeline, has to be fast enough to perform six multiplications in one-quarter of a pipeline cycle if the FMMS is to be expanded to six channels. This requires each multiplication to be completed in 1.27 microseconds. A cheap, but slow serial multiplier that can perform 2's complement, 8x8 multiplication is the AMD25LS14. It is expandable and can perform a 16-x 12-bit multiply in less than 1.2 microseconds, and costs less than \$10 per chip. This chip works very well in the FMMS, although it does require some additional hardware to perform synchronization and clocking. (Refer to Figure A10 for the multiplier synchronization schematic.)

## CHAPTER 5

### SYSTEM SOFTWARE

This chapter deals with the software in the FMMS. The major task of the software is to provide dynamic control of the envelope generators, and supervise the inputs from the ADSL Music System's keyboard. Two programs will be described. The first is a test program which allows the user to experiment with different sounds by allowing him to write the various FM parameters directly into RAM (Random Access Memory) through the use of a monitor program (refer to MUSMON monitor listing in APPENDIX D). The second description is for a program which interfaces the FMMS directly to the keyboard port. This program allows the user to play the FMMS in real time. The parameters for the particular instrument being played will be stored in ROM.

## 5.1 Test Program

### 5.1.1 Parameters

For each note that is played, five registers have to be loaded with values related to the type of sound being synthesized. These registers consist of the modulating phase angle increment (MPA), the carrier phase angle increment (CPA), the constant frequency deviation (FD), the frequency deviation envelope (FENV) and the amplitude envelope (AENV).

5.1.1.1 Scaling. The registers in the frequency generator circuit contain 16 bits (2 fraction bits, 13 integer bits and 1 sign bit). Therefore the value which is loaded into MPA and CPA will be the desired frequency scaled up by four. For instance, a frequency of 1024Hz will have a phase angle increment value of 4096. Keep in mind that the fundamental frequency of the modulated carrier will depend on the ratio of  $f_c$  to  $f_m$  (refer back to chapter two).

The registers in the envelope generating circuit contain only 12 bits (11 magnitude bits and 1 sign bit). Since the value loaded into the frequency deviation registers is the product of the modulating frequency and the modulation index, this value will need to be scaled down. The maximum positive slope increment is  $2^{11}-1$ . This value will therefore represent the maximum modulation frequency ( $2^{13}-1$ ) times the



maximum modulation index (8), for a segment with maximum slope  $[(\text{max amp change})/(\text{min seg duration}) = 1/(1/8) = 8]$ . This product yields  $2^{19}-64$ , therefore each value must be right-shifted by 8 places. The maximum possible value for the frequency deviation is  $8 \times (2^{13}-1)$  or  $2^{16}-8$ . Therefore this value must be right-shifted by 5 places.

Since each envelope consists of four segments (representing the attack, decay, sustain and release of the note), eight parameter values will be needed for each envelope. Each segment has an increment value (which may be negative) along with a duration value. The CPU uses the duration value as a counter to signal when a new segment increment value should be loaded.

5.1.1.2 Timing. In order to properly scale each instantaneous frequency, the parameters must be loaded into their respective pipeline register during the correct clock cycle. To do this, the CPU samples the state of the pipeline clock and after the appropriate number of cycles have elapsed, loads the next parameter into its corresponding pipeline register.

### 5.1.2 Program description

The test program allows the user to experiment with different sounds by programming his own values for the parameters listed in Table 5.1, into the FMMS. (Refer to APENDIX C for program listing and sample test data.)

## 5.2 Keyboard Interface Program

In order to play music in real time, an input port on the FMMS is connected to an output port from the ADSL Music System keyboard processor board. When the keyboard processor detects that a note has been pressed or released, it sends an interrupt to the FMMS processor. The FMMS processor then checks the code in the input port. If it is all zeros it jumps to the released key routine. If not, it splits the code into a lower and upper nibble. It then takes the lower nibble (which is the code for the pitch of the note) and jumps to a table in ROM containing all the parameters for that particular pitch in its highest octave. Then it takes the upper nibble (containing a code for the octave of the note) and divides the frequency dependent parameters in the table by a number which will bring the note into the proper octave. These modified parameter values are then stored in a buffer.

Table 5.1 TEST PROGRAM PARAMETERS

PARAMETER	RANGE	DESCRIPTION
FC	0-7FFFH	CARRIER PHASE ANGLE INCREMENT
FM	0-7FFFH	MODULATION PHASE ANGLE INCREMENT
FD	0-07FFH	FREQUENCY DEVIATION
FENV1-4	0-07FFH (POS) OFFF-0801H (NEG)	FREQUENCY DEVIATION ENVELOPE INCREMENT SEGMENTS 1-4
AENV1-4	0-07FFH (POS) OFFF-0801H (NEG)	AMPLITUDE ENVELOPE INCREMENT SEGMENTS 1-4
SD1-4	01-FF	ENVELOPE SEGMENT DURATION

After the decoding, scaling and storing have been completed, the processor sends the parameters to a routine similar to the Test Program discussed in the previous section. For the third envelope segment (sustain), the processor loads a zero increment into the amplitude and frequency deviation envelope registers. This will cause them to hold their ramp registers constant. The processor then waits for a released key interrupt. Upon receipt of the interrupt, it sends out the last segment increment value (release), to the envelope registers. After the duration of the release segment, the processor clears all pipeline registers and waits for another keypress.

## CHAPTER 6

### CONCLUSIONS

#### 6.1 Future Expansion

The present version of the FMMS is single-channel. However, it represents the basic building block upon which larger, more sophisticated systems can be constructed. In the following paragraphs, a few suggestions are given on how the FMMS may be expanded into a multivoice system.

In order to generate multiple, independent, output waveforms, the existing hardware will need to be time-multiplexed. The limiting factor as to how many additional channels may be added will be the speed of the multiplying pipeline segment. In order to perform the multiplexing, each of the increment registers will write their values into a RAM. Once the RAM's have been loaded, a special counter circuit steps through

the memory, reading both the increment and the accumulated values. These values are then sent to an adder and the result is written back into the RAM accumulator location. This concept is illustrated in Figure 6.1. The special counting circuit has logic which executes the reads and writes at the proper times as well as clocking the holding registers.

In addition, the output circuit would require a separate output section for each channel. This is shown in Figure 6.2 for a system having six channels. A six-bit shift register, clocked at six times the pipeline frequency could be used to trigger the sample and hold (S/H) circuits.

## 6.2 Closing Remarks

The frequency modulation technique used in the FMMS appears to have enough versatility to be able to simulate common musical instrument timbres. More research needs to be done, however, on how the spectrum of different instruments evolves before one can program the FMMS parameters to "accurately" simulate such tones. Strange, yet interesting sounds are easy to produce through experimentation with the Test Program. The FMMS gives an added dimension to music composition in general and particularly to the ADSL Music System.

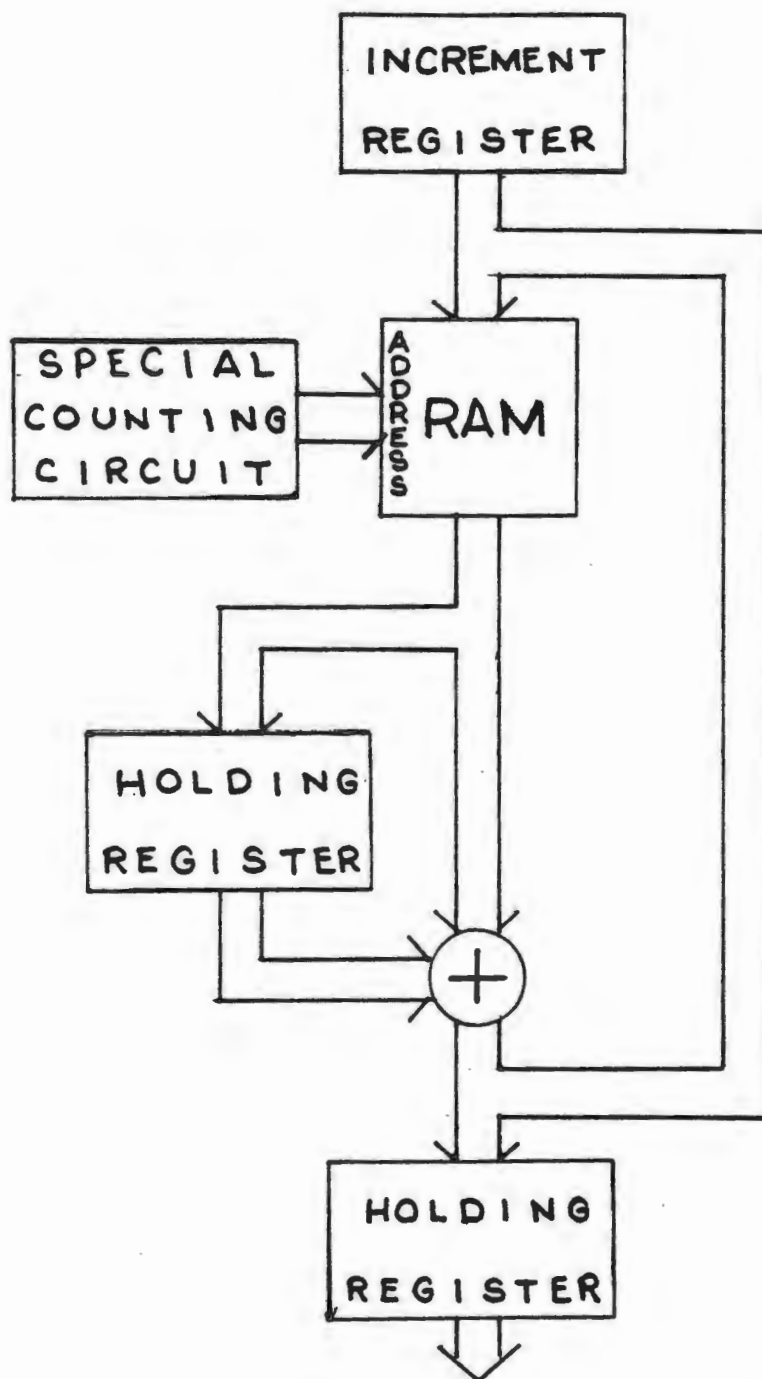
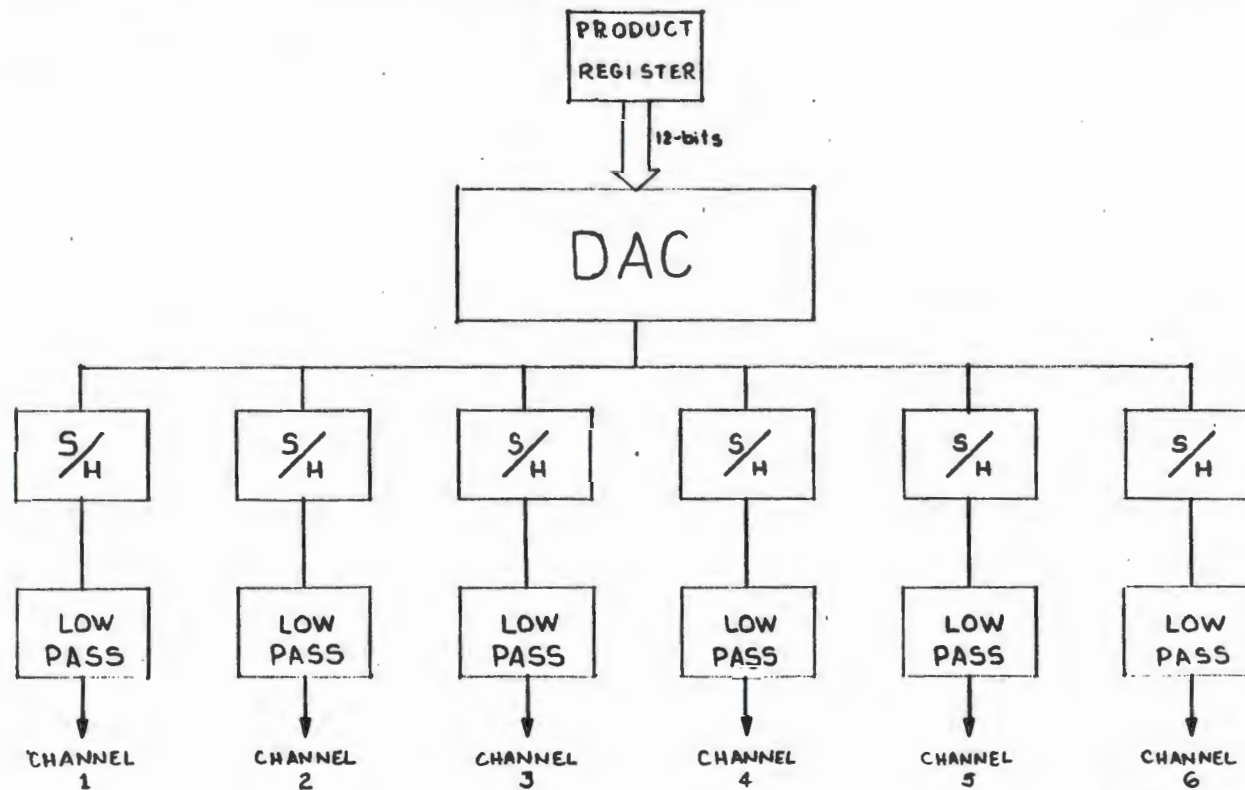


Figure 6.1 MODIFIED INCREMENT REGISTER FOR HANDLING MULTIVOICE

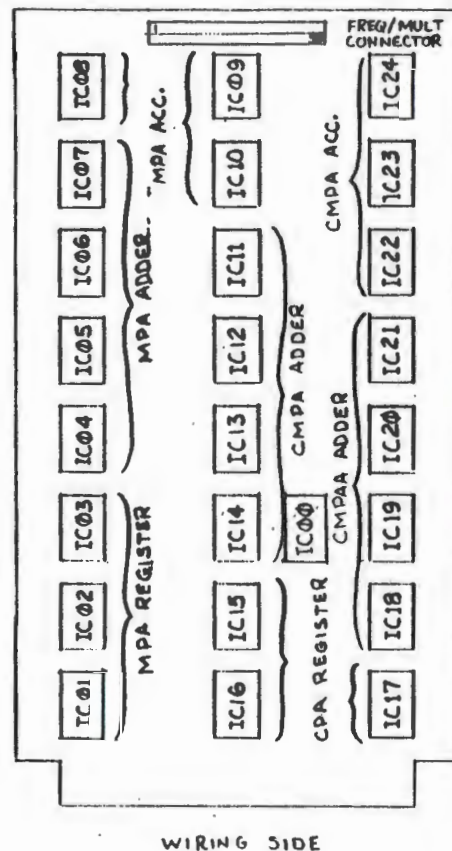


UNIVERSITY OF ILLINOIS ADVANCED DIGITAL SYSTEMS LAB			
MODIFIED FMMS OUTPUT SECTION			
DATE		8-8-81	
DRAWN BY		R.M. KAMINSKY	
REV.		No.	
DESCRIPTION		DATE	
MADE BY		CHK'D BY	

Figure 6.2 MODIFIED OUTPUT SECTION FOR HANDLING MULTIVOICE



**APPENDIX A****FMMS HARDWARE SCHEMATICS**



IN	SIGNAL	IN	SIGNAL
1	+5V	A	GND
2	NC	B	NC
3	NC	C	NC
4	NC	D	NC
5	NC	E	NC
6	NC	F	NC
7	NC	G	NC
8	NC	H	NC
9	NC	I	NC
10	NC	J	NC
11	NC	K	NC
12	NC	L	NC
13	CLK1	M	CPACK
14	CLR	N	MPACK
15	DB14	R	DB15
16	DB12	S	DB13
17	DB10	T	DB11
18	DB08	U	DB09
19	DB06	V	DB07
20	DB04	W	DB05
21	DB02	X	DB03
22	DB00	Y	DB01
23	GND	Z	+5V

SYSTEM BUS  
CONNECTOR

#### DESCRIPTION OF ACRONYMS

MPA - MODULATOR PHASE ANGLE  
 CMPA - CARRIER+MODULATOR PHASE ANGLE  
 CMPAA - CMPA ACCUMULATOR  
 CPA - CARRIER PHASE ANGLE  
 FREQ/MULT - FREQUENCY BOARD TO MULTIPLIER BOARD  
 GND - GROUND  
 CLK - CLOCK  
 CLR - CLEAR  
 DB - DATA BUS  
 MSWA - MODULATION INDEX TIMES SINE WAVE AMPLITUDE

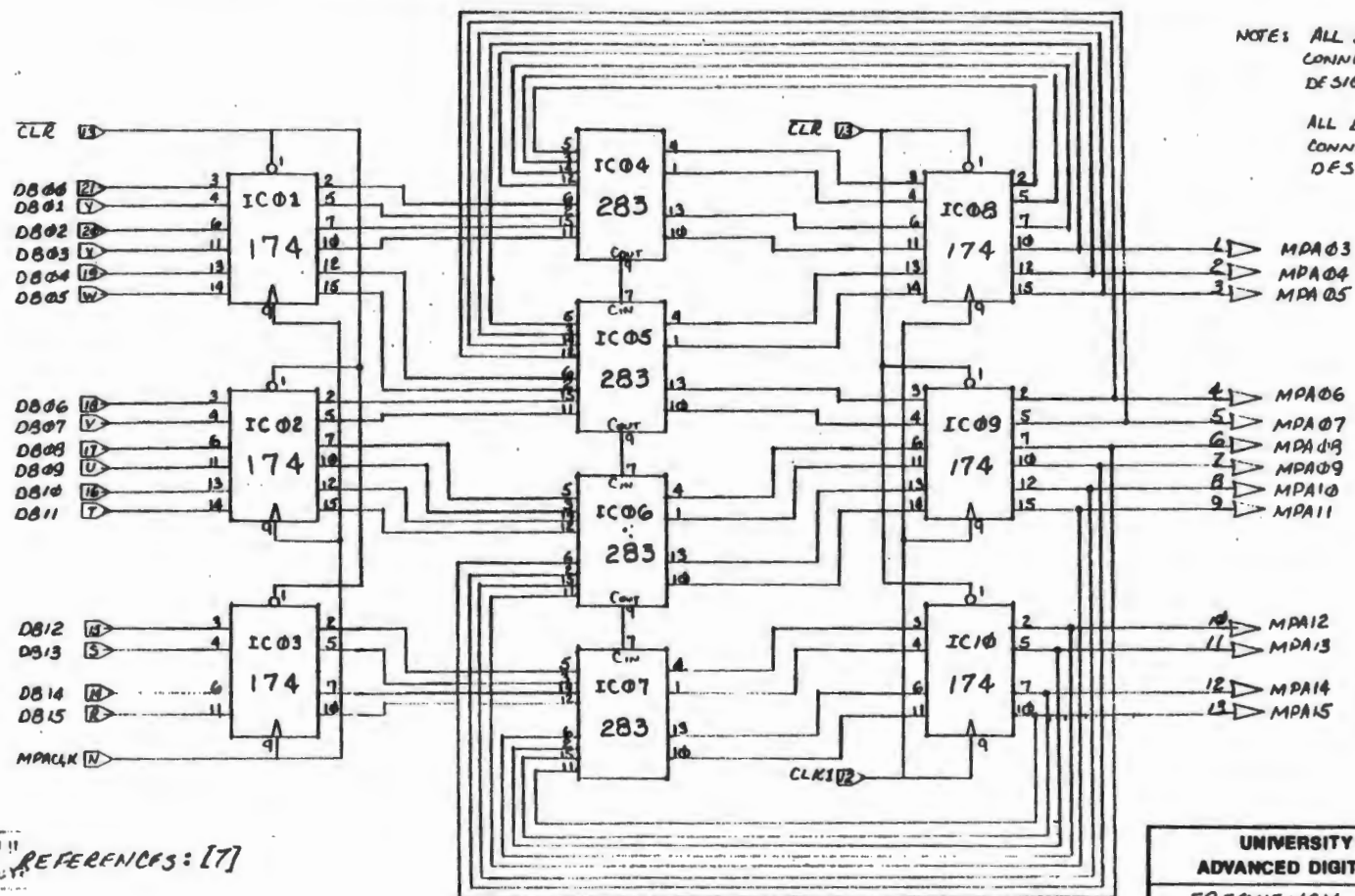
IN	SIGNAL	IN	SIGNAL
1	MPA03	2	MPA04
3	MPA05	4	MPA06
5	MPA07	6	MPA08
7	MPA09	8	MPA10
9	MPA11	10	MPA12
11	MPA13	12	MPA14
13	MPA15	14	NC
15	CMPA03	16	CMPA04
17	CMPA05	18	CMPA06
19	CMPA07	20	CMPA08
21	CMPA09	22	CMPA10
23	CMPA11	24	CMPA12
25	CMPA13	26	CMPA14
27	CMPA15	28	NC
29	NC	30	NC
31	NC	32	NC
33	NC	34	NC
35	MSWA15	36	MSWA14
37	MSWA13	38	MSWA12
39	MSWA11	40	MSWA10
41	MSWA09	42	MSWA08
43	MSWA07	44	MSWA06
45	MSWA05	46	MSWA04
47	MSWA03	48	MSWA02
49	MSWA01	50	MSWA00

FREQ/MULT  
CONNECTOR

UNIVERSITY OF ILLINOIS ADVANCED DIGITAL SYSTEMS LAB	
FREQUENCY GENERATOR BOARD	
COMPONENT LAYOUT & CONNECTOR LIST	
DATE B-B-81	SCALE
DRAWN BY R.M. KAMINSKY	No. 1 of 3

REV.	DESCRIPTION	DATE	MADE BY	CHK'D BY

Figure A1 COMPONENT LAYOUT FOR FREQUENCY GENERATOR BOARD



NOTE: ALL SYSTEM BUS  
CONNECTIONS  
DESIGNATED BY - < 1

ALL EDGE CONNECTING  
CONNECTIONS  
DESIGNATED BY - < 1

REFERENCES: [7]

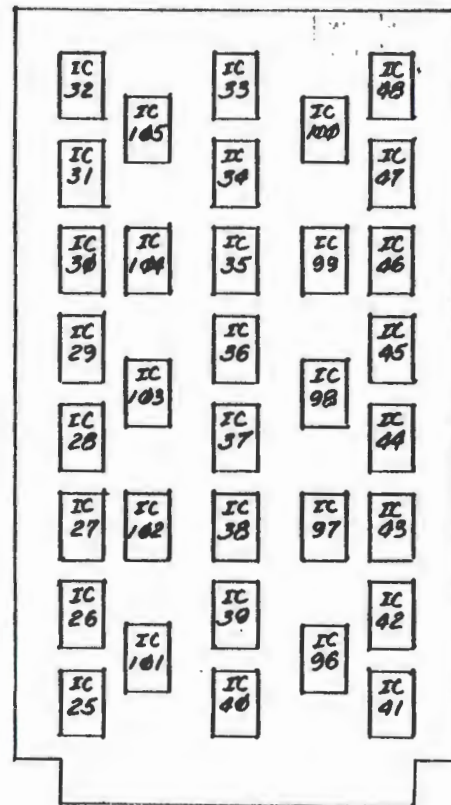
UNIVERSITY OF ILLINOIS ADVANCED DIGITAL SYSTEMS LAB			
FREQUENCY GENERATOR BOARD MPA CIRCUIT			
DATE	8-8-81	SCALE	
DRAWN BY	R M KAMINSKY		
REV.	DESCRIPTION	DATE	MADE BY CHK'D BY

No. 2 of 3

Figure A2 MPA CIRCUIT







WIRING SIDE

OF SYSTEMS  
INTEGRATION

Pin	SIGNAL	Pin	SIGNAL
1	+5V	A	GND
2	MCND00	B	MCND00
3	MCND00	C	MCND00
4	MCND00	D	MCND00
5	MCND00	E	MCND00
6	MCND00	F	MCND00
7	MCND00	G	MCND00
8	NC	J	NC
9	NC	K	NC
10	FENVEL	L	NC
11	FCLK	M	NC
12	CLK	N	NC
13	CLK	P	MCND00
14	NC	R	NC
15	NC	S	NC
16	DB00	T	DB00
17	DB00	U	DB00
18	DB00	V	DB00
19	DB00	W	DB00
20	DB00	X	DB00
21	DB00	Y	DB00
22	GND	Z	+5V

SYSTEM BUS  
CONNECTOR

DESCRIPTION OF ACRONYMS

MCND- MULTIPLICAND

FENV- FREQUENCY DEVIATION  
ENVELOPE

AENV- AMPLITUDE ENVELOPE

FD - FREQUENCY DEVIATION

UNIVERSITY OF ILLINOIS ADVANCED DIGITAL SYSTEMS LAB	
ENVELOPE GENERATOR BOARD	
COMPONENT LAYOUT AND CONN. LIST	
DATE 8-9-81	SCALE
DRAWN BY R. M. KAMINSKY	
REV.	DESCRIPTION
DATE	MADE BY CHK'D BY
No. 1 of 4	

Figure A4 COMPONENT LAYOUT FOR ENVELOPE GENERATOR BOARD

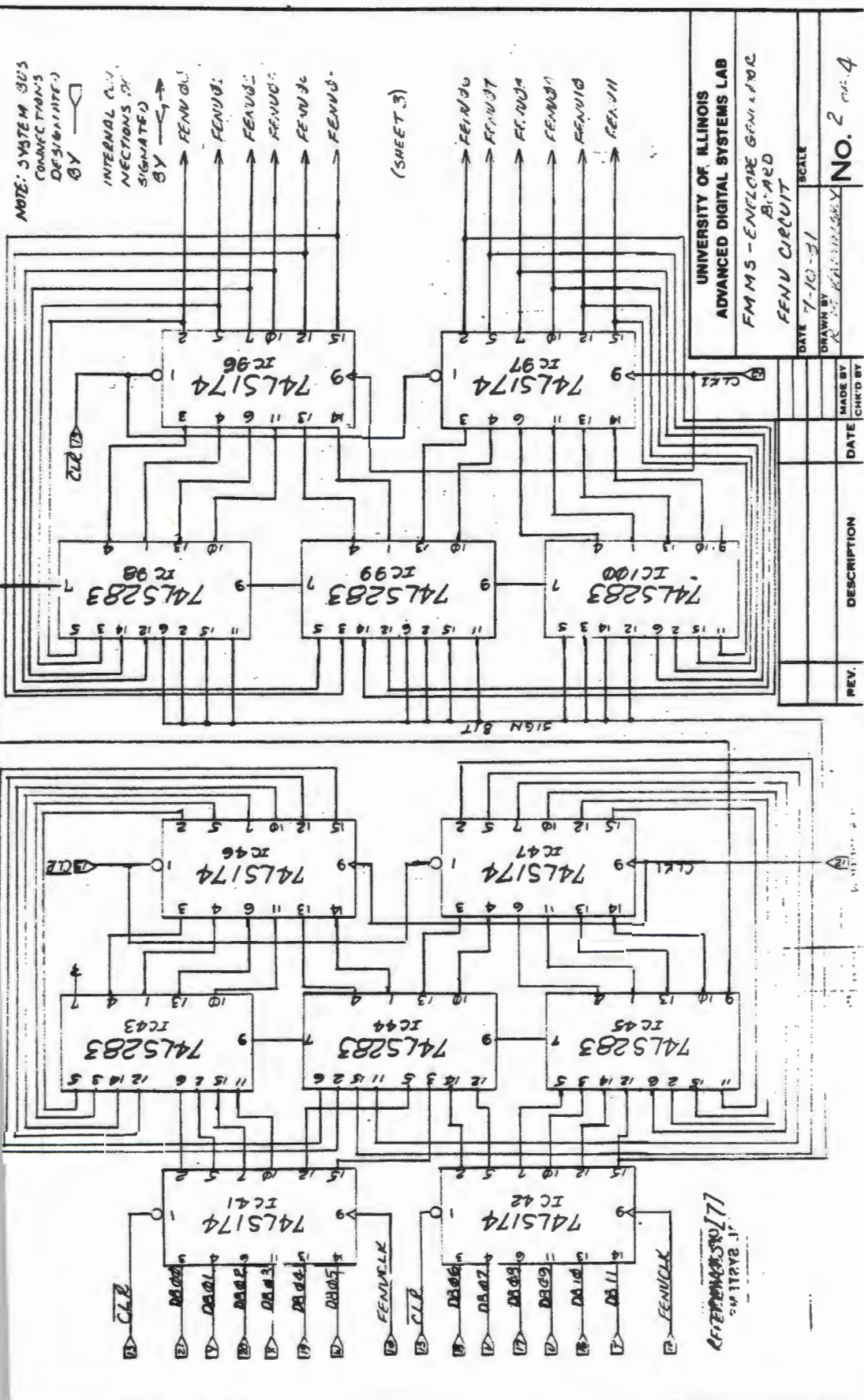
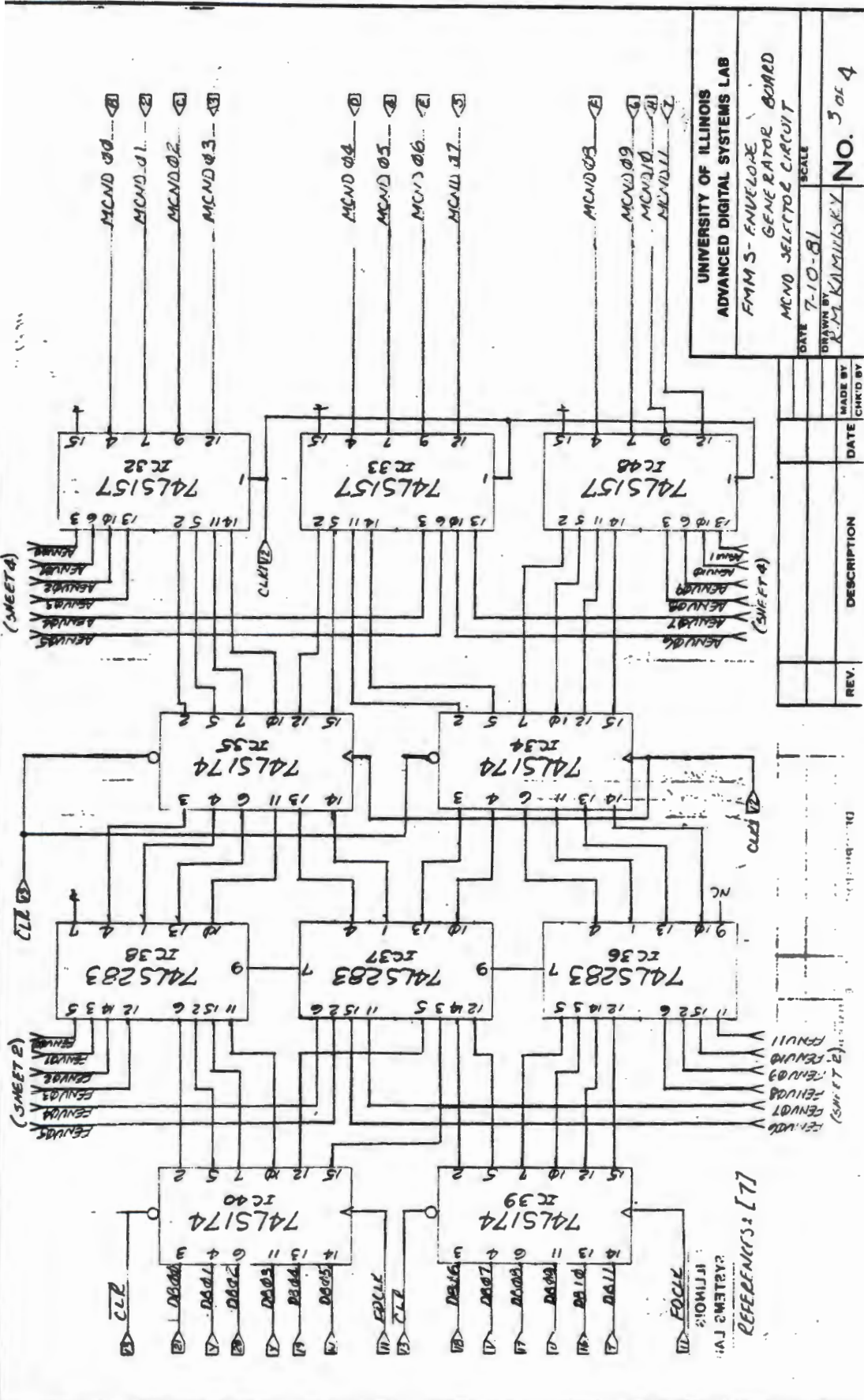


Figure A5 FENV CIRCUIT



UNIVERSITY OF ILLINOIS  
 ADVANCED DIGITAL SYSTEMS LAB  
 FMN S- ENVELOPE  
 GENERATOR BOARD  
 MCND SELECTOR CIRCUIT  
 DATE 7-10-81  
 SCALE  
 DRAWN BY R. M. KAMINSKY  
 MADE BY  
 CHECKED BY  
 DATE  
 DESCRIPTION  
 REV.

No. 3 of 4

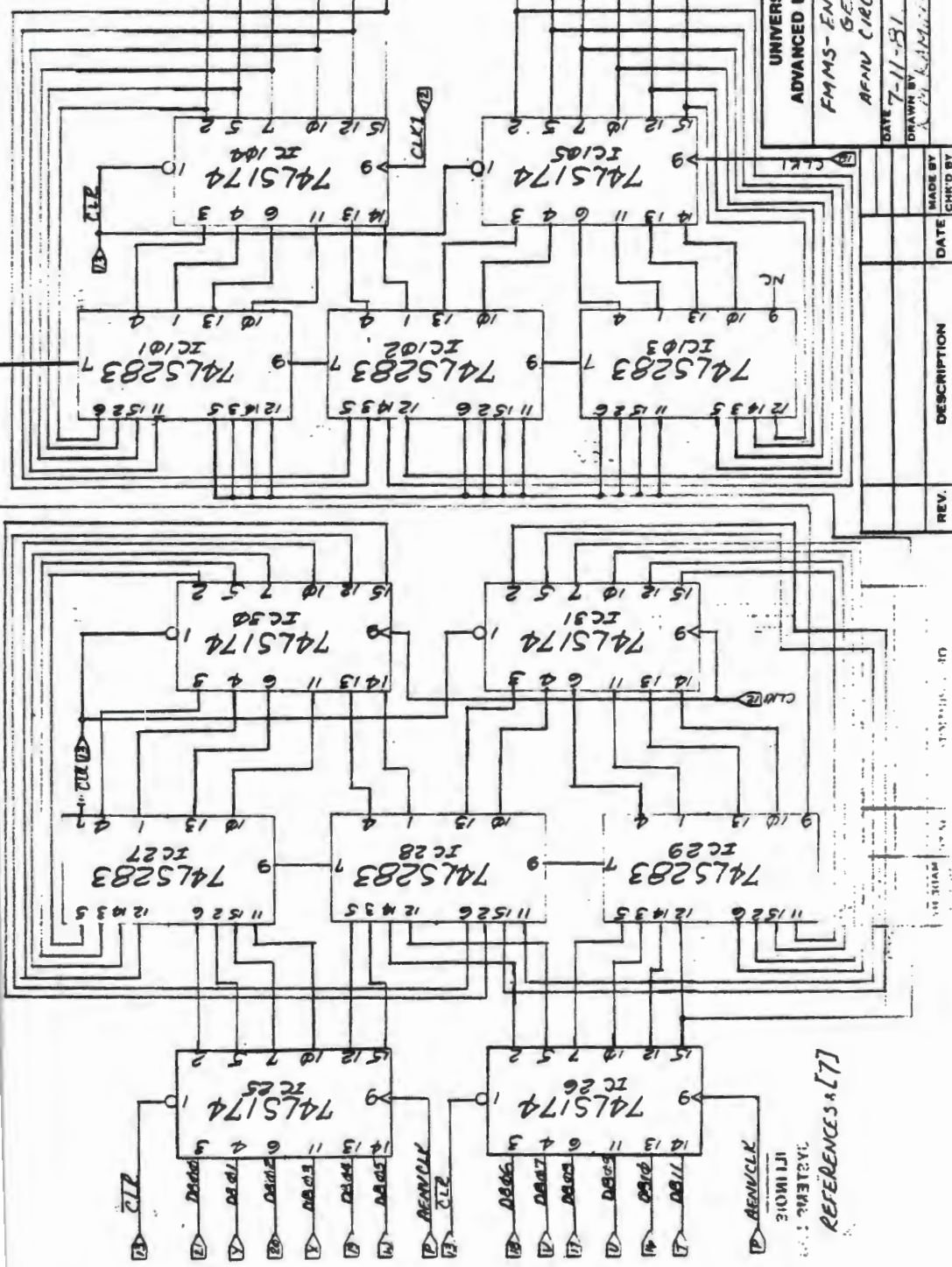
Figure A6 MCND SELECTOR CIRCUIT



NOTE: SYSTEM BUS  
CONNECTIONS  
DESIGNATED BY

INTERNAL CON  
NECTIONS  
DESIGNATED  
BY

AEV00  
AEV01  
AEV02  
AEV03  
AEV04  
AEV05



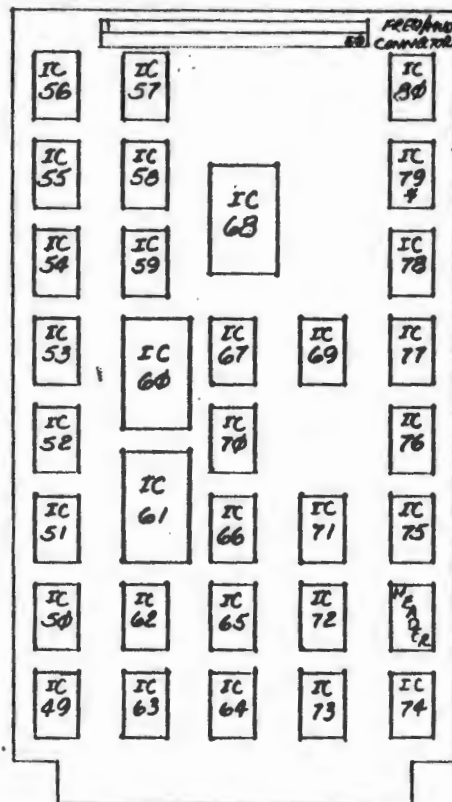
UNIVERSITY OF ILLINOIS  
ADVANCED DIGITAL SYSTEMS LAB  
FMMS-ENVELOPE  
GENERATOR BOARD  
AENV CIRCUIT

DATE 7-11-81  
DRAWN BY J. K. AMUNDSEN  
SCALE  
NO. 4 of 4

REV. DESCRIPTION DATE MADE BY CHK'D BY

Figure A7 AENV CIRCUIT





N	SIGNAL	N	SIGNAL
1	+5V	A	GND
2	MCND01	B	MCND00
3	MCND03	C	MCND02
4	MCND05	D	MCND04
5	MCND07	E	MCND06
6	MCND09	F	MCND08
7	MCND11	H	MCND10
8	+5V	J	+5V
9	CLK2	K	OUT
10	NC	L	MCLK
11	NC	M	NC
12	CLK1	N	NC
13	CLR	P	NC
14	NC	R	NC
15	NC	S	NC
16	NC	T	NC
17	NC	U	NC
18	NC	V	NC
19	NC	W	NC
20	NC	X	NC
21	NC	Y	NC
22	GND	Z	+5V

SYSTEM BUS  
CONNECTOR

#### DESCRIPTION OF ACRONYMS

OUT - DAC OUTPUT VOLTAGE

MCLK - MULTIPLIER CLOCK = 25MHz

CLK1 - PIPELINE CLOCK =  $2^{15}Hz$

CLK2 - TWICE CLK1 =  $2^{16}Hz$

N	SIGNAL	N	SIGNAL
1	MPA03	2	MPA04
3	MPA05	4	MPA06
5	MPA07	6	MPA08
7	MPA09	8	MPA10
9	MPA11	10	MPA12
11	MPA13	12	MPA14
13	MPA15	14	NC
15	CHPA03	16	CHPA04
17	CHPA05	18	CHPA06
19	CHPA07	20	CHPA08
21	CHPA09	22	CHPA10
23	CHPA11	24	CHPA12
25	CHPA13	26	CHPA14
27	CHPA15	28	NC
29	NC	30	NC
31	NC	32	NC
33	NC	34	NC
35	MSWA15	36	MSWA14
37	MSWA13	38	MSWA12
39	MSWA11	40	MSWA10
41	MSWA09	42	MSWA08
43	MSWA07	44	MSWA06
45	MSWA05	46	MSWA04
47	MSWA03	48	MSWA02
49	MSWA01	50	MSWA00

FERR/MULT  
CONNECTOR

UNIVERSITY OF ILLINOIS  
ADVANCED DIGITAL SYSTEMS LAB

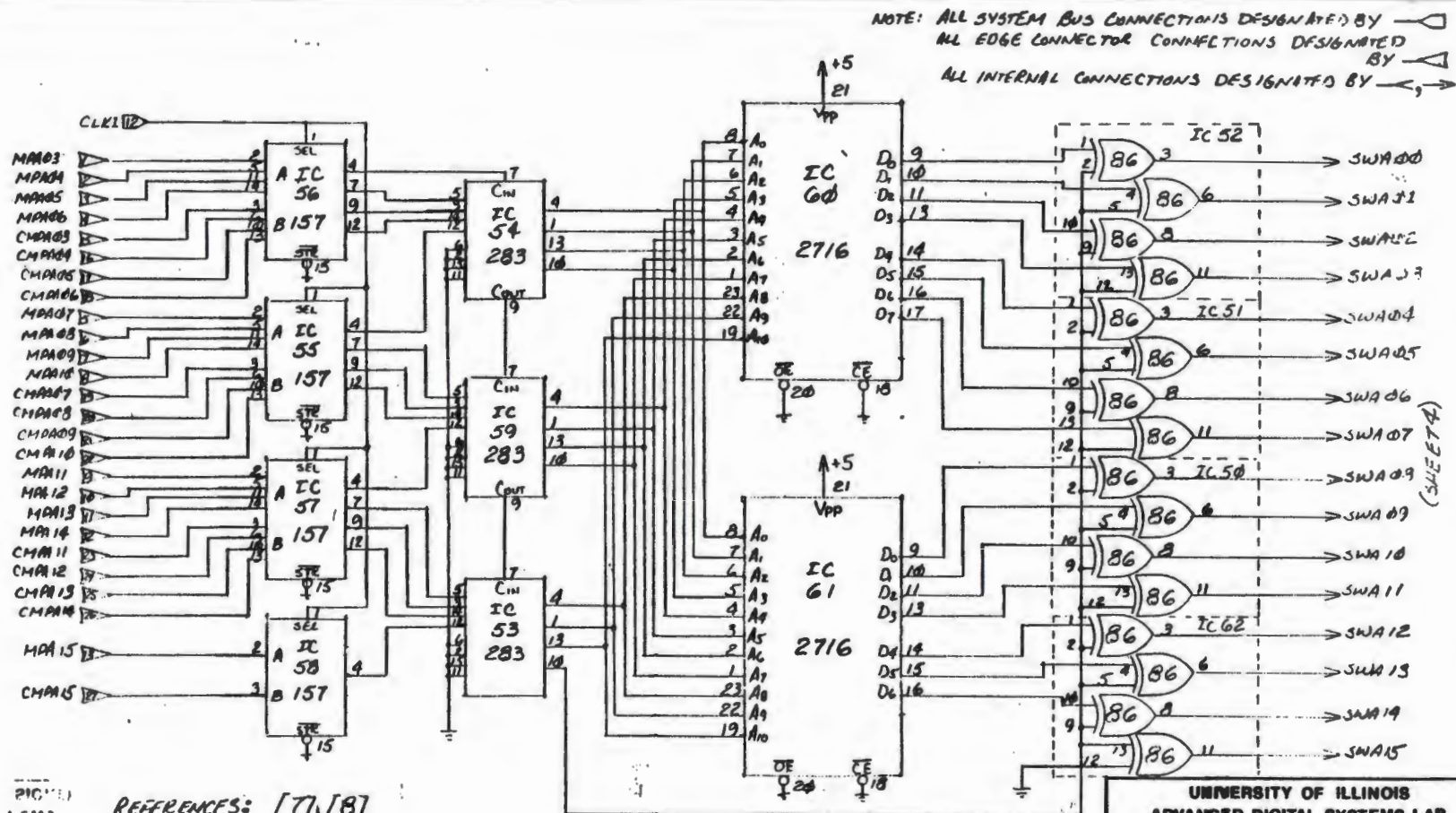
MULTIPLIER BOARD

COMPONENT LAYOUT & CONNECTOR LIST

DATE	8-9-81	SCALE	
DRAWN BY	R. KAMINSKY		
REV.		DATE	
		MADE BY	
		CHK'D BY	

No. 1 of 1

Figure A8 COMPONENT LAYOUT FOR MULTIPLIER BOARD



UNIVERSITY OF ILLINOIS ADVANCED DIGITAL SYSTEMS LAB	
MULTIPLIER BOARD	
MULTIPLIER SELECTOR CIRCUIT	
DATE 8-9-81	SCALE
DRAWN BY R.M. KAMINSKY	NO. 2 OF 4
REV.	DESCRIPTION
DATE	MADE BY
	CHK'D BY

Figure A9 MULTIPLIER SELECTOR CIRCUIT

The diagram shows a hand-drawn circuit for a 3-bit counter. It consists of three integrated circuits: IC 74, IC 75, and IC 80. IC 74 is a 74xx74 dual in-line package (DIP) with a 2K resistor and a 50pF capacitor connected to its input. IC 75 is a 74xx75 DIP with a 10K resistor connected to its input. IC 80 is a 74xx80 DIP. The circuit is powered by a +5V supply. The output of the counter is labeled MULTCLK. The circuit is enclosed in a dashed box, indicating it is a single functional block.

PA. 1. 17

			MULTIPLIER SYNC CIRCUIT	
			DATE	8-9-81
			SCALE	
			DRAWN BY	R.M. KAMINSKY
REV.	DESCRIPTION	DATE	MADE BY	No. 3054
			CHECKED BY	

**Figure A10 MULTIPLIER SYNCHRONIZATION CIRCUIT**

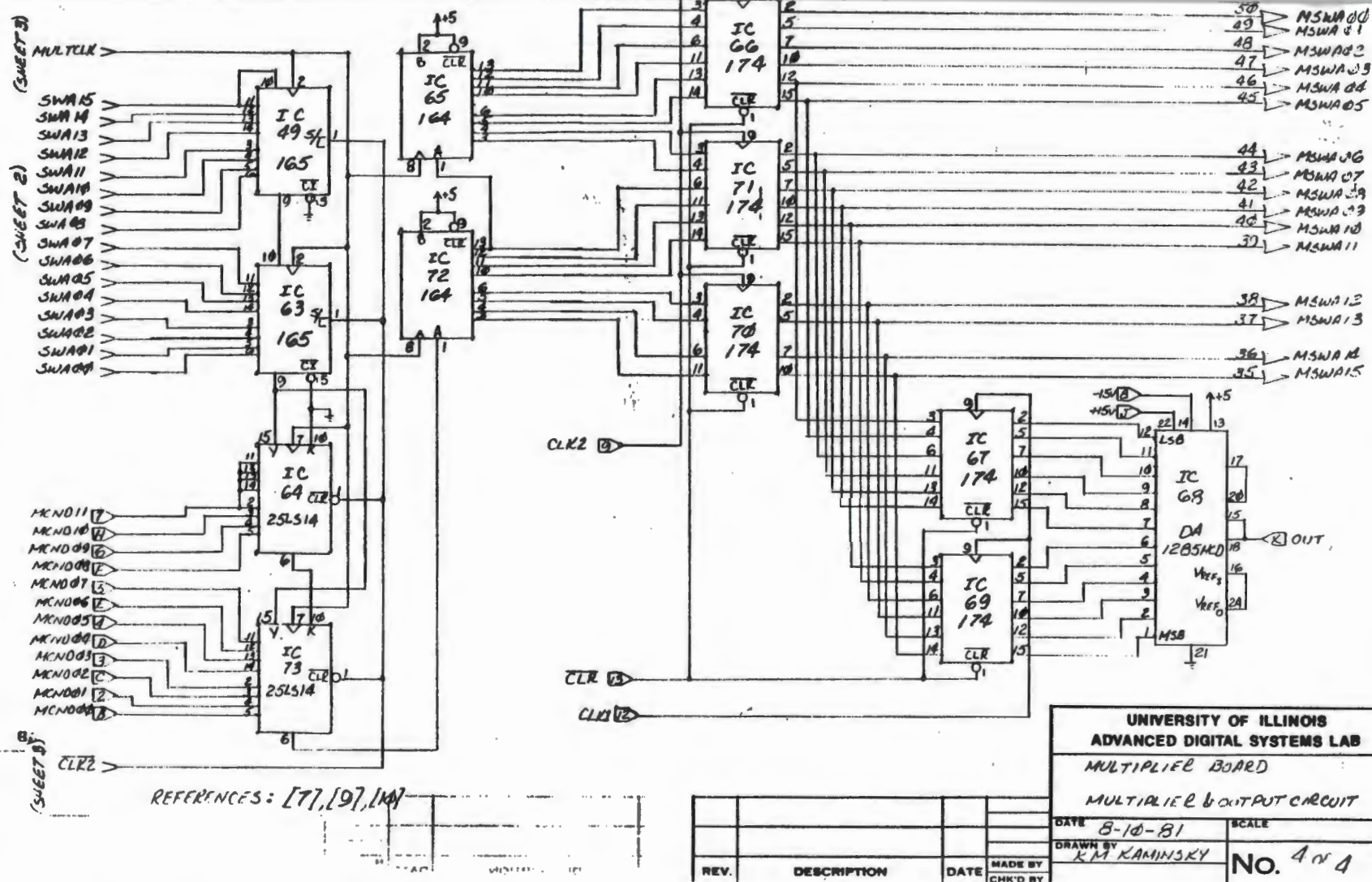
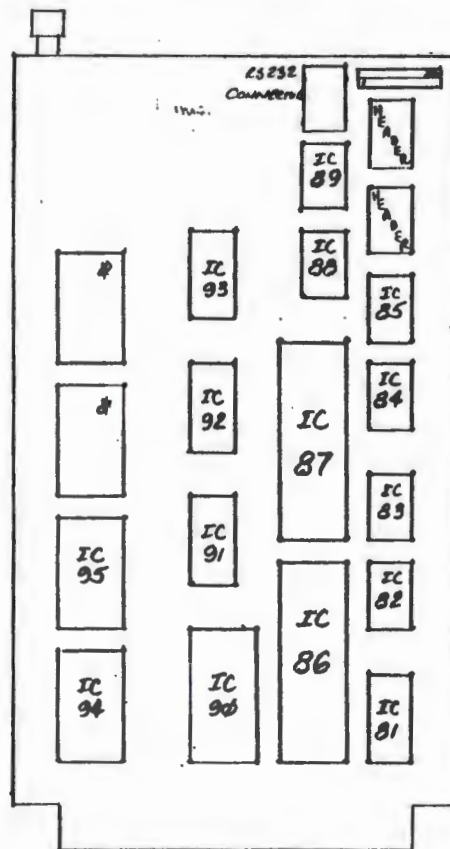


Figure A11 MULTIPLIER & OUTPUT CIRCUIT





COMPONENT SIDE  
3 EMPTY SOCKET

Pin	SIGNAL	Pin	SIGNAL
1	+5V	A	GND
2	NC	B	NC
3	NC	C	NC
4	NC	D	NC
5	NC	E	NC
6	NC	F	NC
7	NC	H	NC
8	NC	J	NC
9	CLK2	K	OUT
10	FRMCLK	L	MCLK
11	FDCLK	M	CPCLK
12	CLK1	N	MAPCLK
13	CLR	P	ASHCLK
14	DB14	R	DB15
15	DB12	S	DB13
16	DB10	T	DB11
17	DB08	U	DB09
18	DB06	V	DB07
19	DB04	W	DB05
20	DB02	X	DB03
21	DB00	Y	DB01
22	GND	Z	+5V

SYSTEM BUS  
CONNECTOR

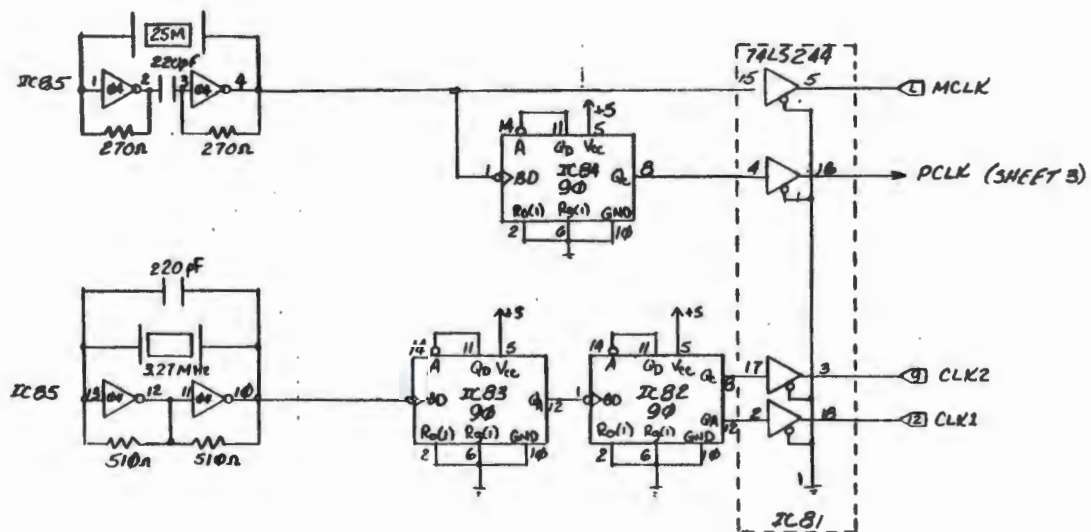
Pin	SIGNAL	Pin	SIGNAL
1	GND	2	D0
3	GND	4	D1
5	GND	6	D2
7	GND	8	D3
9	GND	10	D4
11	GND	12	D5
13	GND	14	D6
15	GND	16	D7
17	GND	18	ACK
19	GND	20	DBF
21	GND	22	NC
23	GND	24	NC
25	GND	26	NC

MUSIC SYSTEM  
CONNECTOR

UNIVERSITY OF ILLINOIS ADVANCED DIGITAL SYSTEMS LAB	
PROCESSOR BOARD	
COMPONENT LAYOUT & CONNECTOR LIST	
DATE 8-10-81	SCALE
DRAWN BY RPT KAMINSKY	No. 1 of 5

REV.	DESCRIPTION	DATE	MADE BY CHK'D BY

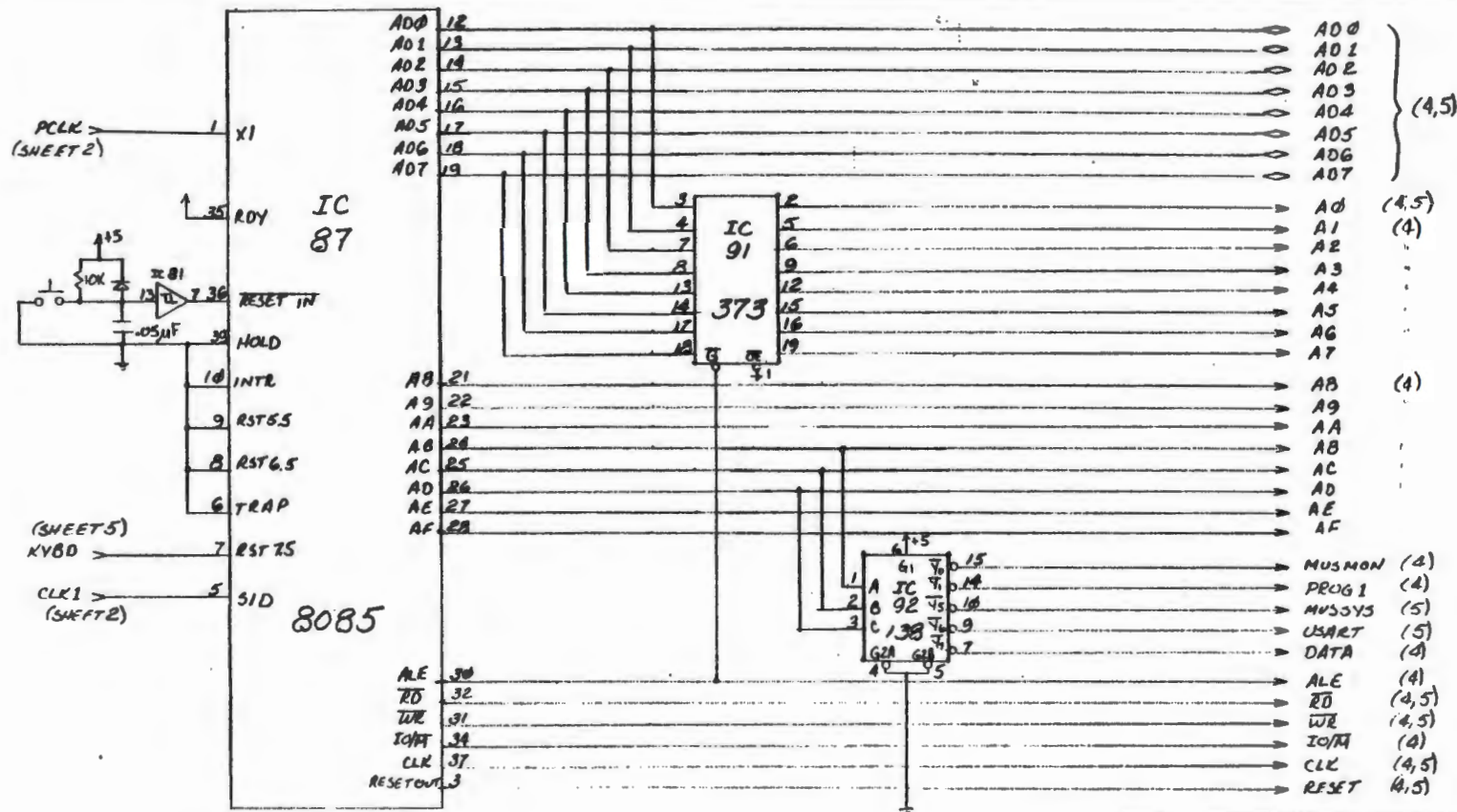
Figure A12 COMPONENT LAYOUT FOR PROCESSOR BOARD



REFERENCES: [7]

UNIVERSITY OF ILLINOIS	
ADVANCED DIGITAL SYSTEMS LAB	
PROCESSOR BOARD	
CLOCK GENERATOR CIRCUIT	
DATE	SCALE
8-10-81	
DRAWN BY	
RM KAMINSKY	
REV.	No. 20: 5

Figure A13 CLOCK GENERATOR CIRCUIT

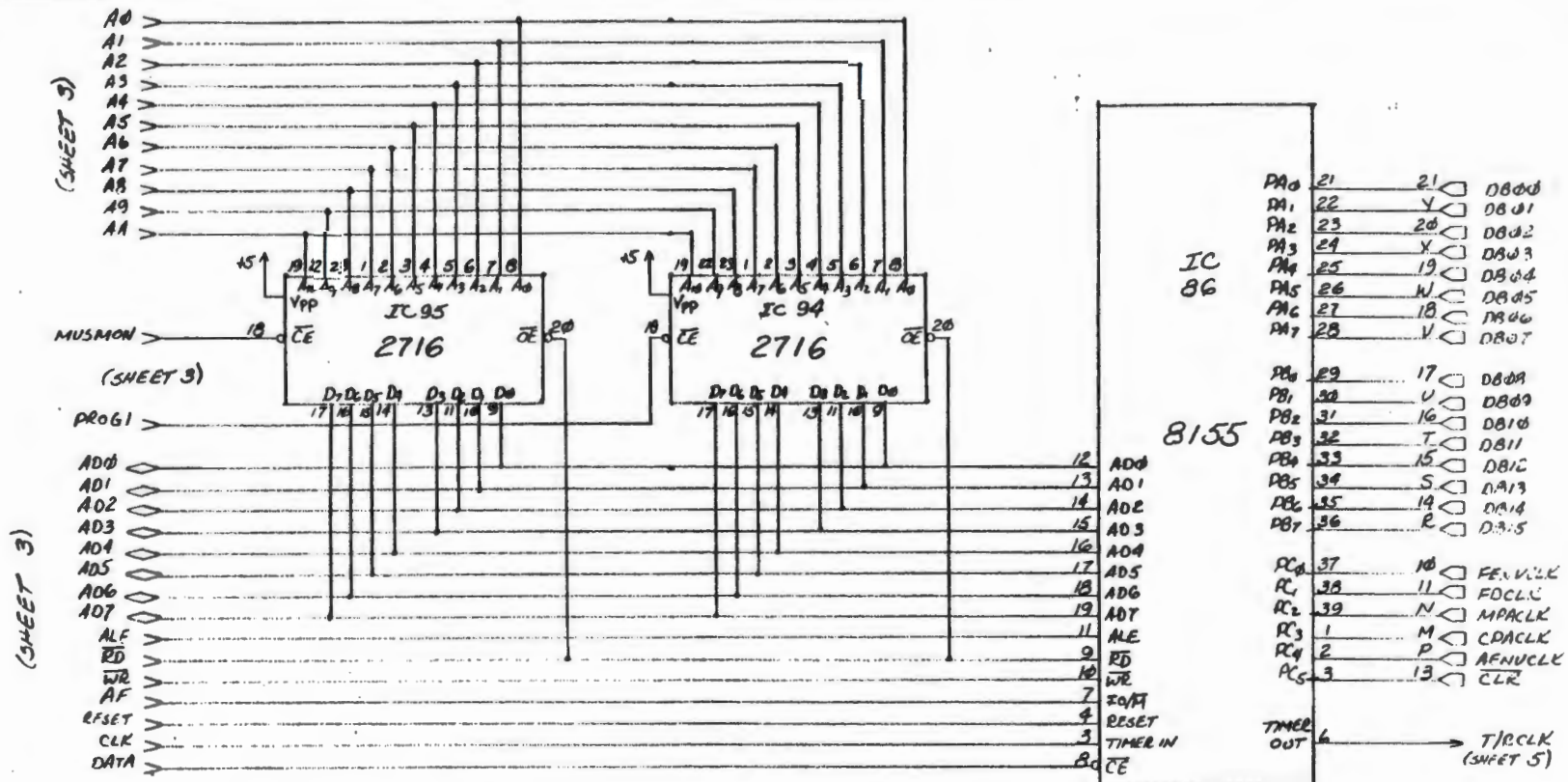


REFERENCES: [7], [11]

UNIVERSITY OF ILLINOIS ADVANCED DIGITAL SYSTEMS LAB	
PROCESSOR BOARD	
CENTRAL PROCESSING UNIT	
DATE 8-10-81	SCALE
DRAWN BY K. M. RAMINSKY	No. 3 of 5

REV.	DESCRIPTION	DATE	MADE BY	CHK'D BY

Figure A14 CENTRAL PROCESSING UNIT



REFERENCES: [8], [11]

NOTE: MUSMON OCCUPIES 0000-07FF  
 PROG1 OCCUPIES 0800-0FFF  
 RAM OCCUPIES 3000-3FFF  
 I/O OCCUPIES FF00-FFFF

UNIVERSITY OF ILLINOIS  
 ADVANCED DIGITAL SYSTEMS LAB

PROCESSOR BOARD

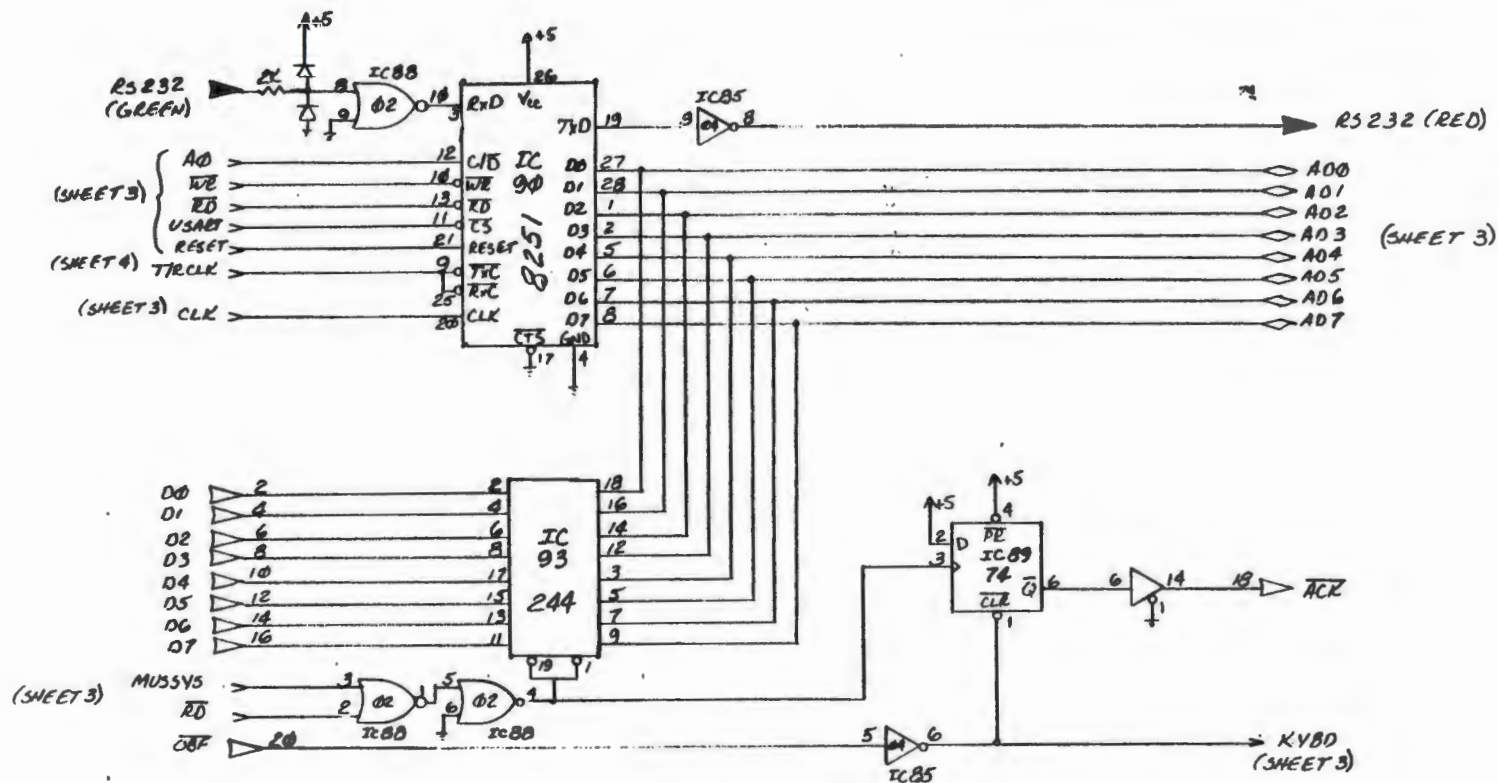
MEMORY & I/O

DATE	8-10-81	SCALE	
DRAWN BY	R.M. KAMINSKY		
MADE BY			
CHK'D BY			

No. 4 of 5

Figure A15 MEMORY & I/O





REFERENCES: [77], [11]

NOTES: ALL EDGE CONNECTOR CONNECTIONS DESIGNATED BY  $\triangleleft$   
 ALL RS 232 HEADER CONNECTIONS DESIGNATED BY  $\blacktriangleleft$   
 ALL INTERNAL CONNECTIONS DESIGNATED BY  $\Rightarrow$   
 USART ADDRESSES: 3000, 3001  
 KEYBOARD PORT ADDRESS: 2800

UNIVERSITY OF ILLINOIS ADVANCED DIGITAL SYSTEMS LAB			
PROCESSOR BOARD			
SERIAL I/O & KEYBOARD PORT			
DATE	B-10-81	SCALE	
DRAWN BY	R.M. KAMINSKY		
REV.	DESCRIPTION	DATE	MADE BY CHK'D BY

No. 5 of 5

Figure A16 SERIAL I/O & KEYBOARD PORT

**APPENDIX B****SYSTEM TIMING DIAGRAM**

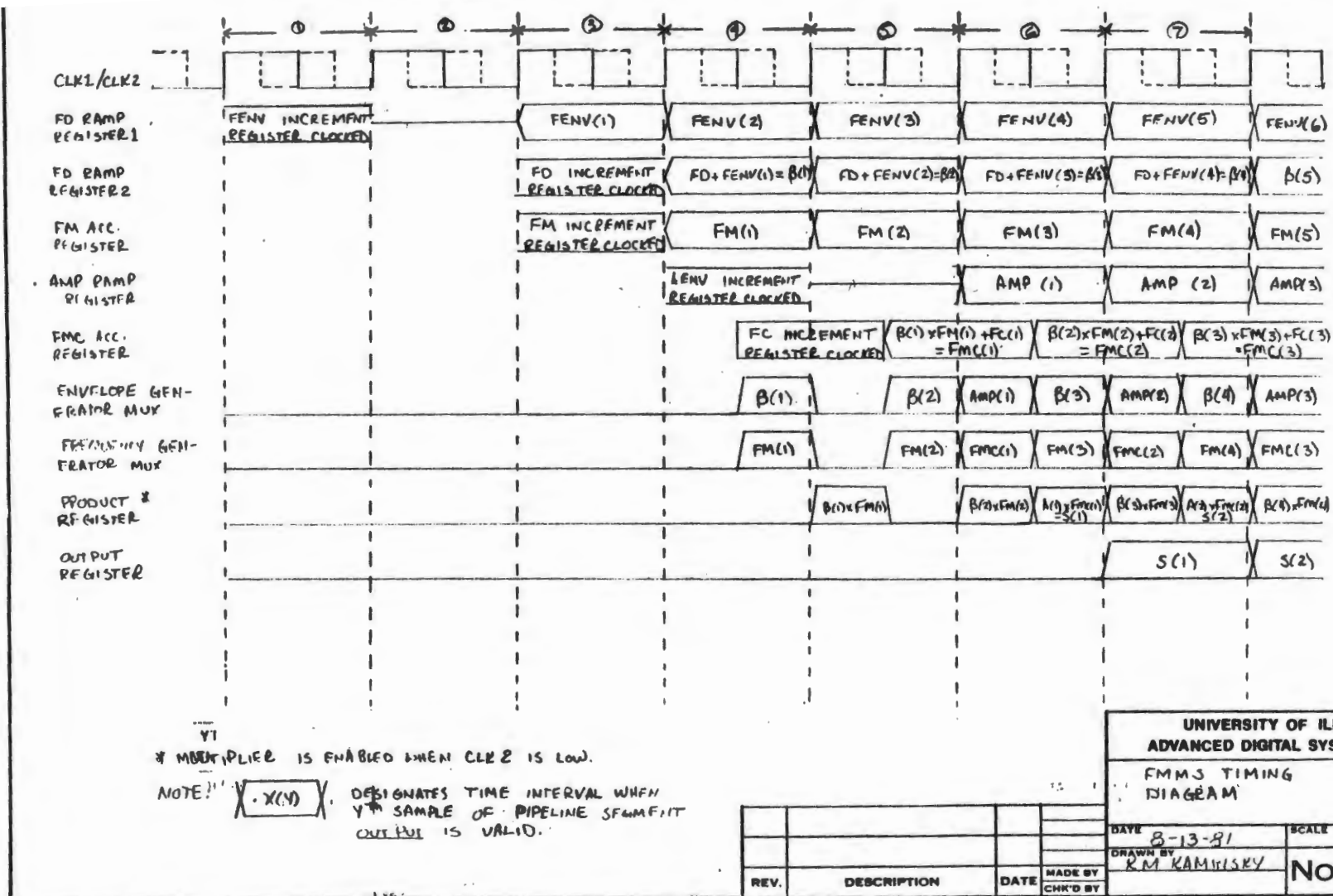


Figure B1 SYSTEM TIMING DIAGRAM

**APPENDIX C****TEST PROGRAM SOFTWARE LISTING**

```

;*****
; THIS IS A TEST PROGRAM TO PLAY A NOTE WITH *
; DYNAMIC CONTROL OF THE MODULATION INDEX AND *
; AMPLITUDE ENVELOPES USING THE ADSL FM MUSIC *
; SYNTHESIZER. *
;*****

```

```

;
;
; TYPE THE FOLLOWING DATA INTO RAM FOR TRUMPET-LIKE SOUNDS:
;
;
;

```

```

; NOTE! FOR WORDS ENTER LOW BYTE IN LOWER ADDRESS!
;
;
;

```

# MONITOR INSERTIONS

LOCATION	DATA	DESCRIPTION
3840,41	01EEH	FENV1
3842,43	0406H	FM
3844,45	0066H	FD
3846,47	03F6H	AENV1
3848,49	0400H	FC
384A	02H	SD1
384B	02H	SD2
384C	04H	SD3
384D	03H	SD4
38A0,A1	0000H	FENV2
38A2,A3	0000H	FENV3
38A4,A5	0F88H	FENV4
38B0,B1	0EC3H	AENV2
38B2,B3	0EC0H	AENV3
38B4,B5	0FD0H	AENV4

00F9		OPRTA	EQU	0F9H ;	OUTPUT PORT A
00FA		OPRTB	EQU	0FAH ;	OUTPUT PORT B
0020		SETCL	EQU	20H ;	COMMAND TO SET CLEAR PIN
00FB		PORTC	EQU	0FBH ;	OUTPUT PORT C
FF01		PORTA	EQU	0FF01H ;	DB LOW BYTE
3800		DATA	EQU	3800H ;	RAM DATA STARTING ADDRESS
0020		RIM	EQU	20H ;	RIM OPCODE
3871		TEST	EQU	3871H ;	BEGINNING ADDRESS OF PROGRAM TEST VALUE
38A0		FENVBUF	EQU	38A0H ;	STARTING ADDRESS OF FENV BUFFER STORAGE
38AE		FENVPTR	EQU	38AEH ;	FENV BUFFER POINTER
38B0		AENVBUF	EQU	38B0H ;	STARTING ADDRESS OF AENV BUFFER STORAGE
38BE		AENVPTR	EQU	38BEH ;	AENV BUFFER POINTER
0800			ORG	0800H	
0800	F3		DI		
0801	21A038		LXI	H, FENVBUF	
0804	22AE38		SHLD	FENVPTR	
0807	21B038		LXI	H, AENVBUF	
080A	22BE38		SHLD	AENVPTR	
080D	AF		XRA	A	
080E	D3FB		OUT	PORTC ;	CLEAR PIPELINE REG'S
0810	3E20		MVI	A, SETCL	
0812	D3FB		OUT	PORTC	
0814	2A4038		LHLD	DATA+64	
0817	2201FF		SHLD	PORTA ;	LOAD FENV1
081A		LOOK	EQU	\$	
081A	3E69		MVI	A, 69H	
081C	327038		STA	TEST-1 ;	DID PROGRAM GET THIS FAR?
081F	20		DB	RIM	
0820	B7		ORA	A	
0821	F21A08		JP	LOOK ;	WAIT FOR CLK1 TO BE HIGH
0824	3E21		MVI	A, 21H	
0826	D3FB		OUT	PORTC ;	CLOCK-IN FENV1
0828	3E69		MVI	A, 69H	

082A	327138		STA	TEST	
		;			
		;			
082D	20	LK05:	DB	RIM	
082E	B7		ORA	A	
082F	FA2D08		JM	LK05	
0832	2A4238		LHLD	DATA+66	
0835	2201FF		SHLD	PORTA ;	LOAD FM
0838		LK10	EQU	\$	
0838	20		DB	RIM	
0839	B7		ORA	A	
083A	F23808		JP	LK10;	WAIT FOR 1 1/2 PIPELINE CLOCK CYCLES
083D		LK15	EQU	\$	
083D	20		DB	RIM	
083E	B7		ORA	A	
083F	FA3D08		JM	LK15	
0842	3E69		MVI	A,69H	
0844	327238		STA	TEST+1	
0847		LK20	EQU	\$	
0847	20		DB	RIM	
0848	B7		ORA	A	
0849	F24708		JP	LK20	
		;			
		;			
084C	3E24		MVI	A,24H	
084E	D3FB		OUT	PORTC ;	CLOCK-IN FM
0850	2A4438		LHLD	DATA+68	
0853	2201FF		SHLD	PORTA ;	LOAD FD
0856	3E22		MVI	A,22H	
0858	D3FB		OUT	PORTC ;	CLOCK-IN FD
085A	3E69		MVI	A,69H	
085C	327338		STA	TEST+2 ;	TEST IF PROGRAM GOT THIS FAR
		;			
		;			
085F	2A4638		LHLD	DATA+70	
0862	2201FF		SHLD	PORTA ;	LOAD AENV1
0865	3E30		MVI	A,30H	
0867	D3FB		OUT	PORTC ;	CLOCK-IN AENV1

```

0869      ; LK25      EQU $
0869      20          DB    RIM
086A      B7          ORA    A
086B      FA6908      JM     LK25 ; WAIT FOR CLK1 LOW
086E      2A4838      LHLD   DATA+72
0871      2201FF      SHLD   PORTA ; LOAD FC
0874      3E28        MVI    A,28H
0876      D3FB        OUT    PORTC ; CLOCK-IN FC
0878      3E69        MVI    A,69H
087A      327438      STA    TEST+3 ; TEST IF PROGRAM GOT THIS FAR
;
;
087D      3A4A38      LDA    DATA+74; LOAD SD1
0880      4F          MOV    C,A
0881      CDCC08      REP:   CALL WAIT
0884      0D          DCR    C
0885      C28108      JNZ    REP
0888      CDD608      CALL   SEG
;
088B      3E69        MVI    A,69H
088D      327538      STA    TEST+4 ; TEST IF PROGRAM GOT THIS FAR
;
0890      3A4B38      LDA    DATA+75; LOAD SD2
0893      4F          MOV    C,A
0894      CDCC08      REP05: CALL WAIT
0897      0D          DCR    C
0898      C29408      JNZ    REP05
089B      CDD608      CALL   SEG
;
;
089E      3A4C38      LDA    DATA+76; LOAD SD3
08A1      4F          MOV    C,A
08A2      CDCC08      REP10: CALL WAIT
08A5      0D          DCR    C
08A6      C2A208      JNZ    REP10
08A9      CDD608      CALL   SEG

```



```

;
;
08AC 3A4D38      LDA  DATA+77;  LOAD SD4
08AF 4F          MOV  C,A
08B0 CDCC08      REP15: CALL WAIT
08B3 0D          DCR  C
08B4 C2B008      JNZ  REP15
08B7 AF          XRA  A
08B8 D3FB        OUT  PORTC ;  CLEAR PIPELINE REG'S
08BA CDCC08      CALL WAIT
08BD CDCC08      CALL WAIT
08C0 CDCC08      CALL WAIT
08C3 CDCC08      CALL WAIT
08C6 CDCC08      CALL WAIT;  PAUSE BEFORE REPEATING NOTE
08C9 C30008      JMP  0800H ;  REPEAT TONE
;
;
08CC 21362D      WAIT: LXI  H,11574D;  DELAY FOR 1/8 SECOND
08CF 2B          LOOP: DCX  H
08D0 7C          MOV  A,H
08D1 B7          ORA  A
08D2 C2CF08      JNZ  LOOP
08D5 C9          RET
;
;
08D6 2AAE38      SEG:  LHLD FENVPTR;  LOAD NEXT FREQ. DEV.
                                ;  ENVELOPE SEGMENT INCREMENT
08D9 7E          MOV  A,M
08DA D3F9        OUT  OPRTA
08DC 23          INX  H
08DD 7E          MOV  A,M
08DE D3FA        OUT  OPRTB
08E0 23          INX  H
08E1 22AE38      SHLD FENVPTR
;
08E4 3E20        MVI  A,SETCL
08E6 D3FB        OUT  PORTC ;  LOWER CLOCK (IF SET)
08E8 3E21        MVI  A,21H
08EA D3FB        OUT  PORTC ;  CLOCK-IN FENV SEG

```

08EC 2ABE38  
08EF 7E  
08F0 D3F9  
08F2 23  
08F3 7E  
08F4 D3FA  
08F6 23  
08F7 22BE38  
08FA 3E30  
08FC D3FB

;  
;  
LHLD AENVPTR; LOAD NEXT AMP. ENVELOPE SEGMENT INCREMENT  
MOV A,M  
OUT OPRTA  
INX H  
MOV A,M  
OUT OPRTB  
INX H  
SHLD AENVPTR  
MVI A,30H  
OUT PORTC ; CLOCK-IN AENV REG

08FE C9  
NO PROGRAM ERRORS

RET  
END

# SYMBOL TABLE

\* 01

A	0007	AENVB	38B0	AENVP	38BE	B	0000
C	0001	D	0002	DATA	3800	E	0003
FENVB	38A0	FENVP	38AE	H	0004	L	0005
LK05	082D	LK10	0838	LK15	083D	LK20	0847
LK25	0869	LOCK	081A	LOOP	08CF	M	0006
OPRTA	00F9	OPRTB	00FA	PORTA	FF01	PORTC	00FB
PSW	0006	REP	0881	REP05	0894	REP10	08A2
REP15	08B0	RIM	0020	SEG	08D6	SETCL	0020
SP	0006	TEST	3871	WAIT	08CC		

APPENDIX D

FMMS MUSMON MONITOR LISTING

```
; LAST MODIFICATION 4:45 PM 7/25/81
; BY BOB KAMINSKY
```

```
;
0000 KBPROC EQU 0 ;KEYBOARD PROC. INPUT PORT
0008 KBRST EQU 8 ; OUTPUT PORT TO RESET KBD PROC
38C0 RSTORG EQU 38C0H ;WHERE RESTART JUMP TABLE IS
0800 KEYPROG EQU 0800H ; 2ND ROM SLOT LOCATION
0010 DELFAC EQU 10H ; DEFAULT DELAY FACTOR FOR MONITOR
0030 SIM EQU 30H ;SIM OP CODE
0020 RIM EQU 20H ;RIM OP CODE
```

```
4021 BAUD EQU 33*4000H; FOR 4800 BAUD SQUARE WAVE
38F0 IOTBL EQU 38F0H; I/O TABLE
001B BRCHR EQU 1BH
383D BRLOC EQU 383DH; BREAK LOCATION
0027 CMD EQU 27H; USART COMMAND WORD
0031 CNCTL EQU 031H; CONSOLE CONTROL
0030 CNIN EQU 030H; CONSOLE IN
0030 CNOUT EQU 030H; CONSOLE OUT
0031 CONST EQU 031H
00F8 CTCTL EQU 0F8H; COUNTER/TIMER CONTROL
00CF CTCMD EQU 0CFH; COUNTER/TIMER COMMAND
000D CR EQU 0DH
3800 DATA EQU 3800H
001B ESC EQU 1BH
000F HCHAR EQU 0FH
00FF INVRT EQU 0FFH
000A LF EQU 0AH
00CE MODE EQU 0CEH
0007 NEWLN EQU 07H
007F PRTYO EQU 7FH
382E REGS EQU DATA+64-16
0002 RBR EQU 2
0038 RSTU EQU 38H
001B TERM EQU 1BH
0001 TRDY EQU 1
00FF UPPER EQU 0FFH
0004 TXBE EQU 04H
00FC CTLO EQU 0FCH; LOW ORDER 8 DIVISION
00FD CTHI EQU 0FDH; UPPER 2 BITS=TIMER MODE
; LOWER 6 BITS=HIGH DIVISION RATE
```

```

; *****
; COLD START                                SYSTEM *
; *****

0000      ORG      0000H
0000      F3
0001      C35100      DI
0008      JMP      STUP
0008      ORG      8
0008      C3C038      JMP      RS1
0010      ORG      10H
0010      C3C338      JMP      RS2


0018      ORG      18H
0018      C3C638      JMP      RS3
0020      ORG      20H
0020      C3C938      JMP      RS4
0024      ORG      24H
0024      C3DE38      JMP      TRAP
0028      ORG      28H
0028      C3CC38      JMP      RS5
002C      ORG      2CH
002C      C3CF38      JMP      RS55
0030      ORG      30H
0030      C3D238      JMP      RS6
0034      ORG      34H
0034      C3D538      JMP      RS65
0038      ORG      38H
0038      C3D838      JMP      RS7
003C      ORG      3CH
003C      C3DB38      JMP      RS75


;
; JUMP TABLE FOR ACCESSING MONITOR ROUTINES
;

003F      C38C00      JMP      WARM      ; WARM START ENTRY POINT
0042      C39302      JMP      CO        ; CHAR OUT, W/ DELAY
0045      C3D602      JMP      GETCH     ; READ IN CHAR
0048      C38703      JMP      NMOUT     ; PRINT HEX NUMBER
004B      C3DD02      JMP      GETHX     ; READ HEX NUMBER
004E      C39E02      JMP      PRMSG     ; PRINT STRING

```

```

0051 3E37      STUP: MVI    A,37H    ; DUMMY CMD WD TO UART TO SET UP SOFT RESET
0053 D331      OUT     CNCTL
0055 3E40      MVI     A,40H    ; SOFTWARE RESET USART
0057 D331      OUT     CNCTL
0059 3ECE      MVI     A,MODE
005B D331      OUT     CNCTL    ; OUTPUT MODE TO USART

```

```

;
; SET UP RESTART JUMP TABLE IN RAM
; TO GO TO THE ROM BREAKPOINT
; ROUTINE
;

```

```

005D 160A      MVI     D,10      ; COUNTER
005F 21C038    LXI     H,RSTORG  ; POINT TO RAM RST TABLE
0062 017600    LXI     B,GO
0065 36C3      STLP: MVI     M,0C3H ; JUMP OP CODE
0067 23        INX     H
0068 71        MOV     M,C      ; ADDRESS OF "GO"
0069 23        INX     H
006A 70        MOV     M,B
006B 23        INX     H
006C 15        DCR     D        ; CHECK COUNTER

```

```

006D C26500    JNZ     STLP      ; REPEAT LOOP
0070 3EDF      MVI     A,11011111B ; DISABLE INTERRUPT LEVELS
0072 30        DB      SIM      ; SIM INSTRUCTION
0073 C36803    JMP     INUST    ; BRANCH TO COMPLETE INIT

```

```

;
GO:
0076 223438    SHLD    LSAVE
0079 E1        POP     H
007A 223638    SHLD    PSAVE
007D F5        PUSH    PSW
007E 210200    LXI     H,2
0081 39        DAD     SP
0082 223838    SHLD    SSAVE
0085 F1        POP     PSW
0086 313438    LXI     SP,ASAVE+1
0089 C35002    JMP     ADR0UT

```

```

;*****
; PRINT SIGNON MESSAGE                                SYSTEM *
;*****
008C      215F04    WARM:                                ; WARM START ENTRY POINT
008C      CD9E02    SOMSG: LXI      H,SGNON
008F      C39500          CALL     PRMSG
0092          JMP      GETCM

;*****
; COMMAND RECOGNIZING ROUTINE
;*****
0095      312E38    GETCM: LXI      SP,MSTAK
0098      0E3E          MVI      C,'>'
009A      CDAF02          CALL     ECHO

;
009D      CDD602    GTC03: CALL     GETCH
00A0      CDAF02          CALL     ECHO
00A3      79          MOV      A,C
00A4      010A00          LXI      B,NCMDS
00A7      219304          LXI      H,CTAB
00AA      BE          GTC05: CMP      M
00AB      CAB600          JZ       GTC10
00AE      23          INX      H
00AF      0D          DCR      C
00B0      C2AA00          JNZ      GTC05
00B3      C3C802          JMP      ERROR
00B6      217D04    GTC10: LXI      H,CADR
00B9      09          DAD      B
00BA      09          DAD      B
00BB      7E          MOV      A,M
00BC      23          INX      H
00BD      66          MOV      H,M
00BE      6F          MOV      L,A
00BF      E9          PCHL

;
00C0      0E02    DCM05: MVI      C,2

;
00C2      CD1103          CALL     GETNM
00C5      D1          POP      D
00C6      E1          POP      H
00C7      CDAA02    DCM05: CALL     CROUT
00CA      CD4702          CALL     ADDR

```



00CD	0E20	DCM10:	MVI	C, ' '
00CF	CDAF02		CALL	ECHO
00D2	7E		MOV	A, M
00D3	CD8703		CALL	NMOUT
00D6	CD6102		CALL	BREAK
00D9	DACD02		JC	EXIT
00DC	CD5603		CALL	HIL0
00DF	DACD02		JC	EXIT
00E2	23		INX	H
00E3	7D		MOV	A, L
00E4	E60F		ANI	OFH
00E6	C2CD00		JNZ	DCM10
00E9	C3C700		JMP	DCM05
;				
00EC	CDDD02	GCMD:	CALL	GETHX
00EF	D20101		JNC	GCM05
00F2	7A		MOV	A, D
00F3	FE0D		CPI	CR
00F5	C2C802		JNZ	ERROR
00F8	213638		LXI	H, PSAVE
00FB	71		MOV	M, C
00FC	23		INX	H
00FD	70		MOV	M, B
00FE	C30701		JMP	GCM10
0101	7A	GCM05:	MOV	A, D
0102	FE0D		CPI	CR
0104	C2C802		JNZ	ERROR
0107	C3EC03	GCM10:	JMP	RSTTF
;				
;				
010A	21CC05	CCMD:	LXI	H, CMSG
010D	CD9E02		CALL	PRMSG
0110	C39500		JMP	GETCM

```

; NEW FORMAT FOR OUTPUT COMMAND:
; B <PORT>, <DATA>
0113 CDDD02 0CMD: CALL GETHX
0116 D2C802 JNC ERROR
0119 7A MOV A,D
011A FE20 CPI ' '
011C CA2401 JZ 0C05
011F FE2C CPI ' '
0121 C2C802 JNZ ERROR
0124 C5 0C05: PUSH B ; PUT PORT # ON STACK
0125 CDDD02 CALL GETHX
0128 D2C802 JNC ERROR

```

```

012B 7A MOV A,D
012C FE0D CPI CR
012E C2C802 JNZ ERROR
0131 C5 PUSH B ; PUT DATA ON STACK
0132 CD3902 CALL SETUP
0135 C1 POP B
0136 D1 POP D
0137 7B MOV A,E
0138 32F138 STA IOTBL+1
013B 79 MOV A,C
013C CDF038 CALL IOTBL
013F C39500 JMP GETCM

```

```

;
0142 CDDD02 1CMD: CALL GETHX
0145 D2C802 JNC ERROR
0148 7A MOV A,D
0149 FE3D CPI '='
014B CA5301 JZ 1CM01
014E FE0D CPI CR
0150 C2C802 JNZ ERROR
0153 C5 1CM01: PUSH B
0154 CD3902 CALL SETUP
0157 C1 POP B
0158 79 MOV A,C
0159 32F438 STA IOTBL+4
015C CDF338 CALL IOTBL+3
015F 4F MOV C,A
0160 CD8703 CALL NMOUT
0163 CDAA02 CALL CROUT
0166 C39500 JMP GETCM

```

0169	0E03	; MCM05:	MVI	C, 3
016B	CD1103		CALL	GETNM
016E	C1		POP	B
016F	E1		POP	H
0170	D1		POP	D
0171	CD7701		CALL	MCM05
0174	C39500		JMP	GETCM
0177	E5	MCM05:	PUSH	H
0178	62		MOV	H, D
0179	6B		MOV	L, E
017A	7E		MOV	A, M
017B	60		MOV	H, B
017C	69		MOV	L, C
017D	77		MOV	M, A
017E	03		INX	B
017F	78		MOV	A, B
0180	B1		ORA	C
0181	C8		RZ	
0182	13		INX	D
0183	E1		POP	H

0184	CD5603		CALL	HIL0
0187	D0		RNC	
0188	C37701		JMP	MCM05
018B	0E01	; SCMD:	MVI	C, 1
018D	CD1103		CALL	GETNM
0190	E1		POP	H
0191	C39F01		JMP	SCM10
0194	7A	SCM05:	MOV	A, D
0195	FE20		CPI	' '
0197	CA9F01		JZ	SCM10
019A	FE2C		CPI	' '
019C	C29500		JNZ	GETCM
019F	7E	SCM10:	MOV	A, M
01A0	CD8703		CALL	NMOUT
01A3	0E2D		MVI	C, ' - '
01A5	CDAF02		CALL	ECHO
01A8	CDDD02		CALL	GETHX
01AB	D2AF01		JNC	SCM15
01AE	71		MOV	M, C

01AF	23	SCM15:	INX	H
01B0	7D		MOV	A,L
01B1	E60F		ANI	OFH
01B3	C29401		JNZ	SCM05
01B6	CDAA02		CALL	CROUT
01B9	CD4702		CALL	ADRD
01BC	0E20		MVI	C, ' '
01BE	CDAF02		CALL	ECHO
01C1	C39401		JMP	SCM05
;				
01C4	CDD602	XCMD:	CALL	GETCH
01C7	CDAF02		CALL	ECHO
01CA	79		MOV	A,C
01CB	FE0D		CPI	CR
01CD	C2D601		JNZ	XCM05
01D0	CDA403		CALL	REGDS
01D3	C39500		JMP	GETCM
01D6	4F	XCM05:	MOV	C,A
01D7	CDD503		CALL	RGADR
01DA	C5		PUSH	B
01DB	E1		POP	H
01DC	0E20		MVI	C, ' '
01DE	CDAF02		CALL	ECHO
01E1	79		MOV	A,C
01E2	323A38		STA	TEMP
01E5	3A3A38	XCM10:	LDA	TEMP
01E8	FE20		CPI	' '
01EA	CAF201		JZ	XCM15
01ED	FE2C		CPI	' '
01EF	C29500		JNZ	GETCM

01F2	7E	XCM15:	MOV	A,M
01F3	B7		ORA	A
01F4	CACD02		JZ	EXIT
01F7	E5		PUSH	H
01F8	5E		MOV	E,M
01F9	1638		MVI	D,DATA/256
01FB	23		INX	H
01FC	46		MOV	B,M
01FD	D5		PUSH	D
01FE	D5		PUSH	D
01FF	E1		POP	H
0200	C5		PUSH	B
0201	7E		MOV	A,M
0202	CD8703		CALL	NMOUT
0205	F1		POP	PSW
0206	F5		PUSH	PSW
0207	B7		ORA	A
0208	CA1002		JZ	XCM20
020B	2B		DCX	H
020C	7E		MOV	A,M
020D	CD8703		CALL	NMOUT
0210	0E2D	XCM20:	MVI	C,'-'
0212	CDAF02		CALL	ECHO
0215	CDDD02		CALL	GETHX
0218	D23002		JNC	XCM30
021B	7A		MOV	A,D
021C	323A38		STA	TEMP
021F	F1		POP	PSW
0220	E1		POP	H
0221	B7		ORA	A
0222	CA2702		JZ	XCM25
0225	70		MOV	M,B
0226	2B		DCX	H

```

0227 71 XCM25: MOV M,C
0228 110300 XCM27: LXI D,RTABS
022B E1 POP H
022C 19 DAD D
022D C3E501 JMP XCM10
0230 7A XCM30: MOV A,D
0231 323A38 STA TEMP
0234 D1 POP D
0235 D1 POP D
0236 C32802 JMP XCM27

;
0239 01F038 SETUP: LXI B,10TBL
023C 118606 LXI D,TBL1
023F 210500 LXI H,5
0242 19 DAD D
0243 CD7701 CALL MCM05
0246 C9 RET

```

```

;*****
; ADRD UTILITY *

```

```

; INPUTS: HL-ADDRESS TO BE DISPLAYED *
; CALLS: NMOUT *
; DESTROYS: A *
; FUNCTION: OUTPUTS TO THE CONSOLE THE ADDRESS CONTAINED IN THE HL *
; REGISTER PAIR *
;*****

```

```

0247 7C ADRD: MOV A,H
0248 CD8703 CALL NMOUT
024B 7D MOV A,L
024C CD8703 CALL NMOUT
024F C9 RET

;
0250 F5 ADROUT: PUSH PSW
0251 C5 PUSH B
0252 D5 PUSH D
0253 0E23 MVI C,'#'
0255 CDAF02 CALL ECHO
0258 2A3638 LHLD PSAVE
025B CD4702 CALL ADRD
025E C3CD02 JMP EXIT

```

```

*****
;          BREAK                                UTILITY      *
;          OUTPUTS: CARRY=1 IF ESCAPE CHARACTER INPUT      *
;                      =0 IF ANY OTHER CHARACTER OR NO CHARACTER *
;          DESTROYS: A,F/F'S                                *
;          FUNCTION: BREAK IS USED TO SENSE AN ESCAPE CHARACTER FROM THE USER. *
;                      IF NO CHARACTER IS PENDING, OR IF THE CHARACTER IS NOT *
;                      AN ESCAPE, THEN A FAILURE RETURN (CARRY=0) IS TAKEN. *
;                      IN THIS CASE, THE CHARACTER IS LOST. IF THE CHARACTER *
;                      IS AN ESCAPE, THEN RETURN IS SUCCESSFUL (CARRY=1). *
*****
0261  DB31  BREAK:  IN      CONST      ;GET URART STATUS
0263  E602          ANI      RBR
0265  CAD302      JZ      FRET      ;RETURN FAILURE IF NO CHAR
0268  DB30  BR05:  IN      CNIN      ;ELSE, GET CHAR
026A  E67F          ANI      PRTYO
026C  FE1B          CPI      BRCHR
026E  CA0004      JZ      SRET      ;IF ESCAPE, THEN SUCCSEFULL RETURN
0271  FE13          CPI      13H
0273  C2D302      JNZ      FRET      ;IF NOT <CTR>S, THEN FAIL RETURN
0276  DB31  BR10:  IN      CONST      ;ELSE, WAIT FOR NEW CHAR
0278  E602          ANI      RBR
027A  CA7602      JZ      BR10
027D  C36802      JMP      BR05
*****
;          CI                                UTILITY      *
;          OUTPUTS: A-CHARACTER FROM CONSOLE                *
;          DESTROYS: A,F/F'S                                *
;          FUNCTION: CI WAITS UNTIL A CHARACTER HAS BEEN ENTERED AT THE CONSOLE *
;                      AND THEN RETURNS THE CHARACTER, VIA THE A REGISTER, TO THE *
;                      CALLING ROUTINE. *
*****
0280  DB31  CI:    IN      CONST
0282  E602          ANI      RBR
0284  CA8002      JZ      CI
0287  DB30          IN      CNIN
0289  C9          RET

```



```

;*****
;      CNVBN                                UTILITY      *
;      INPUTS: C-ASCII CHARACTER '0'-'9' OR 'A'-'F'      *
;      OUTPUTS: A- 0 TO F HEX                              *
;      DESTROYS: A,F/F'S                                    *
;      FUNCTION: CNVBN CONVERTS THE ASCII REPRESENTATION OF A HEX CHARACTER *
;                  INTO ITS CORRESPONDING BINARY VALUE.  CNVBN DOES NOT CHECK *
;                  THE VALIDITY OF ITS INPUT.                *
;*****
028A  79      CNVBN:  MOV      A,C
028B  D630      SUI      '0'
028D  FE0A      CPI      10D
028F  F8        RM
0290  D607      SUI      7
0292  C9        RET

;*****
;      C0                                UTILITY      *
;      INPUTS: C-CHARACTER TO OUTPUT TO CONSOLE          *
;      OUTPUTS: C-CHARACTER OUTPUT TO CONSOLE            *
;      DESTROYS: A,F/F'S                                    *
;      FUNCTION: C0 WAITS UNTIL THE CONSOLE IS READY TO ACCEPT A CHARACTER *
;                  AND THEN SENDS THE INPUT ARGUMENT TO THE CONSOLE.      *
;*****
0293  DB31      C0:    IN      CONST
0295  E601      ANI      TRDY
0297  CA9302     JZ      C0
029A  79        MOV      A,C
029B  D330      OUT      CNOUT
029D  C9        RET

029E  7E      PRMSG:  MOV      A,M
029F  FEFF      CPI      OFFH      ; END OF STRING?
02A1  C8        RZ
02A2  4E        MOV      C,M
02A3  CD9302     CALL     C0
02A6  23        INX      H
02A7  C39E02     JMP      PRMSG

```

```

; *****
;      CROUT                                UTILITY      *
;      CALLS: ECHO                                *
;      DESTROYS: A,B,C,F/F'S                        *
;      FUNCTION: CROUT SENDS A CARRIAGE RETURN (AND HENCE A LINE FEED) TO *
;
;
;      THE CONSOLE DEVICE.                                *
; *****
02AA  0E0D  CROUT: MVI      C,CR
02AC  C3AF02  JMP      ECHO
; *****
;      ECHO                                UTILITY      *
;      INPUTS: C-CHARACTER TO ECHO TO CONSOLE          *
;      OUTPUTS: C-CHARACTER ECHOED TO CONSOLE          *
;      CALLS: CO                                        *
;      DESTROYS: A,B,F/F'S                            *
;      FUNCTION: ECHO TAKES A SINGLE CHARACTER AS INPUT AND, VIA THE *
;                  MONITOR, SENDS THAT CHARACTER TO THE USER CONSOLE. *
;                  A CARRIAGE RETURN IS ECHOED AS A CARRIAGE RETURN LINE *
;                  FEED, AND AN ESCAPE IS ECHOED AS '$'. *
; *****
02AF  41      ECHO:  MOV      B,C
02B0  3E1B      MVI      A,ESC
02B2  B8        CMP      B
02B3  C2B802    JNZ      ECH05
02B6  0E24      MVI      C,'$'
02B8  CD9302    ECH05:  CALL  CO
02BB  3E0D      MVI      A,CR
02BD  B8        CMP      B
02BE  C2C602    JNZ      ECH10
02C1  0E0A      MVI      C,LF
02C3  CD9302    CALL     CO
02C6  48        ECH10:  MOV      C,B
02C7  C9        RET

```

```

; *****
; ERROR UTILITY *
; CALLS: ECHO, CROUT, GETCM *
; DESTROYS: A, B, C, F/F'S *
; FUNCTION: ERROR PRINTS THE AN ASTERISK ON THE CONSOLE, FOLLOWED BY *
; A CARRIAGE RETURN LINE FEED, AND THEN RETURNS CONTROL *
; TO THE COMMAND RECOGNIZER. *
; *****
02C8 0E23 ERROR: MVI C, '#'
02CA CDAF02 CALL ECHO
02CD CDAA02 EXIT: CALL CROUT
02D0 C39500 JMP GETCM
; *****
; FRET UTILITY *
; DESTROYS: CARRY *
; FUNCTION: FRET SETS THE CARRY FALSE, DENOTING FAILURE, AND THEN *
; RETURNS TO THE CALLER OF THE ROUTINE INVOKING FRET. *
; *****
02D3 37 FRET: STC
02D4 3F CMC
02D5 C9 RET
; *****
; GETCH UTILITY *
; *****
;
; OUTPUTS: C-NEXT CHARACTER IN INPUT STREAM *
; CALLS: CI *
; DESTROYS: A, C, F/F'S *
; FUNCTION: GETCH RETURNS THE NEXT CHARACTER IN THE INPUT STREAM TO *
; THE CALLING ROUTINE. *
; *****
02D6 CD8002 GETCH: CALL CI
02D9 E67F ANI PRTYO
02DB 4F MOV C, A
02DC C9 RET

```

```

*****
GETHEX                                UTILITY
OUTPUTS: BC-16 BIT INTEGER
        D-CHARACTER WHICH TERMINATED INTEGER
        CARRY=1 IF FIRST CHARACTER NOT TERMINATOR
        =0 IF FIRST CHARACTER IS TERMINATOR
CALLS: GETCH,ECHO,VALDL,VALDG,CNVBN,ERROR
DESTROYS: A,B,C,D,E,F/F'S
FUNCTION: GETHX ACCEPTS A STRING OF HEX DIGITS FROM THE INPUT
        STREAM AND RETURNS THEIR VALUE AS A 16-BIT BINARY INTEGER.
        IF MORE THAN 4 HEX DIGITS ARE ENTERED, ONLY THE LAST 4
        ARE USED. THE NUMBER TERMINATES WHEN A VALID DELIMITER
        IS ENCOUNTERED. THE TERMINATOR IS RETURNED AS AN OUTPUT
        OF THE FUNCTION. ILLEGAL CHARACTERS CAUSE AN ERROR IN-
        DICATION. IF THE FIRST CHARACTER IN THE INPUT STREAM
        IS NOT A VALID DELIMETER, GETHX WILL RETURN WITH THE
        CARRY BIT SET TO 1; OTHERWISE, THE CARRY BIT IS SET TO 0
        AND THE CONTENTS OF BC PAIR ARE UNDEFINED.
*****
02DD    E5    GETHX:  PUSH    H
02DE    210000    LXI     H,0
02E1    1E00    MVI     E,0
02E3    CDD602    GHX05:  CALL   GETCH
02E6    CDAF02    CALL   ECHO
02E9    CD4704    CALL   VALDL
02EC    D2FB02    JNC    GHX10
02EF    51      MOV     D,C
02F0    E5      PUSH    H
02F1    C1      POP     B
02F2    E1      POP     H
02F3    7B      MOV     A,E
02F4    B7      ORA     A
02F5    C20004    JNZ     SRET
02F8    CAD302    JZ      FRET
02FB    CD2C04    GHX10:  CALL   VALDG
02FE    D2C802    JNC     ERROR
0301    CD8A02    CALL   CVNBN
0304    1EFF      MVI     E,INVRT
0306    29      DAD     H
0307    29      DAD     H
0308    29      DAD     H

```

0309	29	DAD	H
030A	0600	MVI	B, 00
030C	4F	MOV	C, A
030D	09	DAD	B
030E	C3E302	JMP	GHX05

```

*****
; GETNM                                UTILITY *
; INPUTS: C-COUNT OF NUMBERS TO FIND IN INPUT STREAM *
; OUTPUTS: TOP OF STACK-NUMBERS FOUND IN REVERSE ORDER *
; CALLS: GETHX, HILO, ERROR *
; DESTROYS: A, B, C, D, E, H, L, F/F'S *
; FUNCTION: GETNM FINDS A SPECIFIED COUNT OF NUMBERS, BETWEEN 1 AND 3, *
;           INCLUSIVE, IN THE INPUT STREAM AND RETURNS THEIR VALUES *
;           ON THE STACK. IF 2 OR MORE NUMBERS ARE REQUESTED, THEN *
;           THE FIRST MUST BE LESS THAN OR EQUAL TO THE SECOND, OR *
;           THE FIRST AND SECOND NUMBERS WILL BE SET EQUAL. THE LAST *
;           NUMBER REQUESTED MUST BE TERMINATED BY A CARRIAGE RETURN *
;           OR AN ERROR WILL RESULT. *
*****

```

0311	2E03	GETNM:	MVI	L, 03
0313	79		MOV	A, C
0314	E603		ANI	03
0316	C8		RZ	
0317	67		MOV	H, A
0318	CDDD02	GNM05:	CALL	GETHX
031B	D2C802		JNC	ERROR
031E	C5		PUSH	B
031F	2D		DCR	L
0320	25		DCR	H
0321	CA2D03		JZ	GNM10
0324	7A		MOV	A, D
0325	FE0D		CPI	CR
0327	CAC802		JZ	ERROR
032A	C31803		JMP	GNM05
032D	7A	GNM10:	MOV	A, D
032E	FE0D		CPI	CR
0330	C2C802		JNZ	ERROR
0333	01FFFF		LXI	B, 0FFFFH
0336	7D		MOV	A, L
0337	B7		ORA	A
0338	CA4003		JZ	GNM20

033B	C5	GNM15:	PUSH	B
033C	2D		DCR	L
033D	C23B03		JNZ	GNM15
0340	C1	GNM20:	POP	B
0341	D1		POP	D
0342	E1		POP	H
0343	CD5603		CALL	H1L0
0346	D24B03		JNC	GNM25
0349	54		MOV	D,H
034A	5D		MOV	E,L

034B	E3	GNM25:	XTHL	
034C	D5		PUSH	D
034D	C5		PUSH	B
034E	E5		PUSH	H
034F	3D	GNM30:	DCR	A
0350	F8		RM	
0351	E1		POP	H
0352	E3		XTHL	
0353	C34F03		JMP	GNM30

```

;*****
;      HILO                                UTILITY      *
;      INPUTS: DE-16 BIT INTEGER                      *
;               HL-16 BIT INTEGER                      *
;      OUTPUTS: CARRY=0 IF HL<DE                      *
;               =1 IF HL>=DE                          *
;      DESTROYS: A,F/F'S                              *
;      FUNCTION: HILO COMPARES THE TWO 16-BIT INTEGERS IN HL AND DE PAIRS. *
;               THE INTEGERS ARE TREATED AS UNSIGNED TWO'S COMPLEMENT *
;               NUMBERS. THE CARRY BIT IS SET ACCORDING TO THE RESULT *
;               OF THE COMPARISON.                      *
;*****

```

0356	C5	HILO:	PUSH	B
0357	47		MOV	B,A
0358	23		INX	H
0359	7C		MOV	A,H
035A	B5		ORA	L
035B	2B		DCX	H
035C	37		STC	
035D	CA6503		JZ	HL05
0360	7D		MOV	A,L
0361	93		SUB	E
0362	7C		MOV	A,H
0363	9A		SBB	D

0364	3F		CMC	
0365	78	HL05:	MOV	A,B
0366	C1		POP	B
0367	C9		RET	
;				
0368	3E27	INUST:	MVI	A,CMD
036A	D331		OUT	CNCTL
036C	3ECF		MVI	A,CTCMD
036E	D3F8		OUT	CTCTL
0370	212140		LXI	H,BAUD
0373	7D		MOV	A,L
0374	D3FC		OUT	CTL0
0376	7C		MOV	A,H
0377	D3FD		OUT	CTHI
0379	DB30		IN	CNIN
037B	210238		LXI	H,MSTAK-44
037E	223838		SHLD	SSAVE
0381	312E38		LXI	SP,MSTAK

0384	C38C00		JMP	SOMSG ; JUMP TO MONITOR
------	--------	--	-----	-------------------------

```

; *****
; NMOUT                                     UTILITY *
; INPUTS: A-8 BIT INTEGER                      *
; CALLS: ECHO,PRVAL                            *
; DESTROYS: A,B,C,F/F'S                        *
; FUNCTION: NMOUT CONVERTS THE 8 BIT, UNSIGNED INTEGER INTO THE A *
;           REGISTER INTO TWO ASCII CHARACTERS. THE ASCII CHARACTERS *
;           ARE THE ONES REPRESENTING THE 8 BITS. THESE TWO *
;           CHARACTERS ARE SENT TO THE CONSOLE FOR DISPLAY. *
; *****

```

0387	F5	NMOUT:	PUSH	PSW
0388	0F		RRC	
0389	0F		RRC	
038A	0F		RRC	
038B	0F		RRC	
038C	CD9A03		CALL	PRVAL
038F	CDAF02		CALL	ECHO
0392	F1		POP	PSW
0393	CD9A03		CALL	PRVAL
0396	CDAF02		CALL	ECHO
0399	C9		RET	



```

*****
; PRVAL UTILITY *
; INPUTS: A-INTEGER, RANGE 0 TO F *
; OUTPUTS: A-ASCII CHARACTER *
; DESTROYS: C *
; FUNCTION: PRVAL CONVERTS THE NUMBER IN THE A REGISTER FROM 0 TO F *
; INTO THE CORRESPONDING ASCII CHARACTER, 0-9,A-F. PRVAL *
; DOES NOT CHECK THE VALIDITY OF THE INPUT. *
*****
039A E60F PRVAL: ANI HCHAR
039C C690 ADI 90H
039E 27 DAA
039F CE40 ACI 40H
03A1 27 DAA
03A2 4F MOV C,A
03A3 C9 RET

03A4 219D04 REGDS: LXI H,RTAB
03A7 4E REG05: MOV C,M
03A8 79 MOV A,C
03A9 B7 ORA A
03AA C2B103 JNZ REG10
03AD CDAA02 CALL CROUT
03B0 C9 RET
03B1 CDAF02 REG10: CALL ECHO
03B4 0E3D MVI C,'='
03B6 CDAF02 CALL ECHO

03B9 23 INX H
03BA 5E MOV E,M
03BB 1638 MVI D,DATA/256
03BD 23 INX H
03BE 1A LDAX D
03BF CD8703 CALL NMOUT
03C2 7E MOV A,M
03C3 B7 ORA A
03C4 CACC03 JZ REG15
03C7 1B DCX D
03C8 1A LDAX D
03C9 CD8703 CALL NMOUT
03CC 0E20 REG15: MVI C,' '
03CE CDAF02 CALL ECHO
03D1 23 INX H
03D2 C3A703 JMP REG05

```

```

03D5 219D04 ;RGADR: LXI H,RTAB
03D8 110300 LXI D,RTABS
03DB 7E RGA05: MOV A,M
03DC B7 ORA A
03DD CAC802 JZ ERROR
03E0 B9 CMP C
03E1 CAE803 JZ RGA10
03E4 19 DAD D
03E5 C3DB03 JMP RGA05
03E8 23 RGA10: INX H
03E9 44 MOV B,H
03EA 4D MOV C,L
03EB C9 RET

```

```

03EC F3 ;RSTTF: DI
03ED 312E38 LXI SP,MSTAK
03F0 D1 POP D
03F1 C1 POP B
03F2 F1 POP PSW
03F3 2A3838 LHLD SSAVE
03F6 F9 SPHL
03F7 2A3638 LHLD PSAVE
03FA E5 PUSH H
03FB 2A3438 LHLD LSAVE
03FE FB EI
03FF C9 RET

```

```

;*****
; SRET UTILITY *
; OUTPUTS: CARRY=1 *
; DESTROYS: CARRY *
; FUNCTION: SRET IS CALLED BY ROUTINS WISHING TO RETURN SUCCESS. *
; SRET SETS THE CARRY TRUE AND THEN RETURNS TO THE CALLER *
; OF THE ROUTINE INVOKING SRET. *
;*****

```

```

0400 37 SRET: STC
0401 C9 RET

```

```

0402 3A3A38 ; STHF0: LDA TEMP
0405 B7 ; ORA A
0406 C0 ; RNZ
0407 0E00 ; MVI C,0
0409 CD0D04 ; CALL STHLF
040C C9 ; RET

; STHLF:
040D D5 ; PUSH D
040E E1 ; POP H
040F 79 ; MOV A,C
0410 E60F ; ANI HCHAR
0412 4F ; MOV C,A
0413 3A3A38 ; LDA TEMP
0416 B7 ; ORA A
0417 C22004 ; JNZ STH05
041A 7E ; MOV A,M
041B E6F0 ; ANI OF0H
041D B1 ; ORA C
041E 77 ; MOV M,A
041F C9 ; RET
0420 7E ; STH05: MOV A,M
0421 E60F ; ANI HCHAR
0423 47 ; MOV B,A
0424 79 ; MOV A,C
0425 0F ; RRC
0426 0F ; RRC
0427 0F ; RRC
0428 0F ; RRC
0429 B0 ; ORA B
042A 77 ; MOV M,A
042B C9 ; RET

```

```

;*****
; VALDG UTILITY *
; INPUTS: C-ASCII CHARACTER *
; OUTPUTS: CARRY=1 IF CHARACTER REPRESENTS VALID HEX DIGIT *
;          =0 OTHERWISE *
; DESTROYS: A,F/F'S *
; FUNCTION: VALDG RETURNS SUCCESS IF ITS INPUT ARGUMENT IS AN ASCII *
;           CHARACTER REPRESENTING A VALID HEX DIGIT, AND FAILURE *
;           OTHERWISE. *
;*****

```

```

042C 79 VALDG: MOV A,C
042D FE30 CPI '0'
042F FAD302 JM FRET
0432 FE39 CPI '9'
0434 FA0004 JM SRET
0437 CA0004 JZ SRET
043A FE41 CPI 'A'

```

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```

043C FAD302 JM FRET
043F FE47 CPI 'G'
0441 F2D302 JP FRET
0444 C30004 JMP SRET
;*****
; VALDL UTILITY *
; INPUTS: C-CHARACTER *
; OUTPUTS: CARRY=1 IF INPUT ARGUMENT IS VALID DELIMETER *
;          =0 OTHERWISE *
; DESTROYS: A,F/F'S *
; FUNCTION: VALDL RETURNS SUCCESS IF ITS INPUT ARGUMENT IS A VALID *
;           DELIMETER CHARACTER (SPACE, COMMA, CARRIAGE RETURN, EQUAL SIGN) *
;           FAILURE OTHERWISE. *
;*****
0447 79 VALDL: MOV A,C
0448 FE2C CPI ','
044A CA0004 JZ SRET
044D FE0D CPI CR
044F CA0004 JZ SRET
0452 FE20 CPI '='
0454 CA0004 JZ SRET
0457 FE3D CPI '='
0459 CA0004 JZ SRET
045C C3D302 JMP FRET
;
045F 0D0A4144 SGNON: DB CR,LF,'ADSL FM MUSIC SYNTHESIZER',CR,LF
0463 534C2046
0467 4D204D55
046B 53494320
046F 53594E54
0473 48455349
0477 5A45520D
047B 0A
047C FF DB OFFH

```

047D	0000	: CADR:	DW	0
047F	C401		DW	XCMD
0481	8B01		DW	SCMD
0483	6901		DW	MCMD
0485	EC00		DW	GCMD
0487	C000		DW	DCMD
0489	C004		DW	RCMD
048B	0905		DW	WCMD
048D	0A01		DW	CCMD
048F	4201		DW	ICMD
0491	1301		DW	OCMD
0493	4F	: CTAB:	DB	'0'
0494	49		DB	'1'
0495	43		DB	'C'
0496	57		DB	'W'
0497	52		DB	'R'
0498	44		DB	'D'
0499	47		DB	'G'
049A	4D		DB	'M'
049B	53		DB	'S'
049C	58		DB	'X'
000A		NCMDS	EQU	\$-CTAB
049D	41	RTAB:	DB	'A'
049E	33		DB	ASAVE - ((ASAVE/256)*256)
049F	00		DB	0
0003		RTABS	EQU	\$-RTAB
04A0	42		DB	'B'
04A1	31		DB	BSAVE - ((BSAVE/256)*256)
04A2	00		DB	0
04A3	43		DB	'C'
04A4	30		DB	CSAVE - ((CSAVE/256)*256)
04A5	00		DB	0
04A6	44		DB	'D'
04A7	2F		DB	DSAVE - ((DSAVE/256)*256)
04A8	00		DB	0
04A9	45		DB	'E'
04AA	2E		DB	ESAVE - ((ESAVE/256)*256)
04AB	00		DB	0
04AC	46		DB	'F'

04AD	32	DB	FSAVE - (( FSAVE/256) *256)
04AE	00	DB	0
04AF	48	DB	'H'
04B0	35	DB	HSAVE - (( HSAVE/256) *256)
04B1	00	DB	0
04B2	4C	DB	'L'
04B3	34	DB	LSAVE - (( LSAVE/256) *256)
04B4	00	DB	0
04B5	4D	DB	'M'
04B6	35	DB	HSAVE - (( HSAVE/256) *256)
04B7	01	DB	1
04B8	50	DB	'P'
04B9	37	DB	PSAVE+1 - ((( PSAVE+1) /256) *256)
04BA	01	DB	1
04BB	53	DB	'S'
04BC	39	DB	SSAVE+1 - ((( SSAVE+1) /256) *256)
04BD	01	DB	1
04BE	00	DB	0
04BF	00	DB	0

04C0	CDDD02	RCMD:	CALL	GETHX
04C3	7A		MOV	A, D
04C4	FE0D		CPI	CR
04C6	C2C802		JNZ	ERROR
04C9	C5		PUSH	B
04CA	CD8002	RCM05:	CALL	CI
04CD	4F		MOV	C, A

04CE	CD9302	CALL	C0
04D1	E67F	ANI	PRTY0
04D3	FE3A	CPI	':'
04D5	C2CA04	JNZ	RCM05
04D8	AF	XRA	A
04D9	57	MOV	D, A
04DA	CD5B05	CALL	BYTE
04DD	5F	MOV	E, A
04DE	CD5B05	CALL	BYTE
04E1	67	MOV	H, A

04E2	CD5B05		CALL	BYTE
04E5	6F		MOV	L, A
04E6	CD5B05		CALL	BYTE
04E9	B7		ORA	A
04EA	C20305		JNZ	RCM15
04ED	C1		POP	B
04EE	C5		PUSH	B
04EF	09		DAD	B
04F0	4B		MOV	C, E
04F1	CD5B05	RCM10:	CALL	BYTE
04F4	77		MOV	M, A
04F5	23		INX	H
04F6	1D		DCR	E
04F7	C2F104		JNZ	RCM10
04FA	CD5B05		CALL	BYTE
04FD	C2C802		JNZ	ERROR
0500	C3CA04		JMP	RCM05
0503	CD5B05	RCM15:	CALL	BYTE
0506	C39500		JMP	GETCM
;				
0509	0E02	WCMD:	MVI	C, 2
050B	CD1103		CALL	GETNM
050E	D1		POP	D
050F	E1		POP	H
0510	7D	WCM05:	MOV	A, L
0511	C610		ADI	10H
0513	4F		MOV	C, A
0514	7C		MOV	A, H
0515	CE00		ACI	0
0517	47		MOV	B, A
0518	7B		MOV	A, E
0519	91		SUB	C
051A	4F		MOV	C, A
051B	7A		MOV	A, D
051C	98		SBB	B
051D	DA2505		JC	WCM10
0520	3E10		MVI	A, 10H
0522	C32805		JMP	WCM15
0525	79	WCM10:	MOV	A, C
0526	C611		ADI	11H



0528 B7 WCM15: GRA A

```

0529 CA5505      JZ      WCM25
052C D5          PUSH    D
052D 5F          MOV     E,A
052E 1600        MVI     D,0
0530 0E3A        MVI     C,':'
0532 CD9302      CALL    C0
0535 7B          MOV     A,E
0536 CD8905      CALL    PBYTE
0539 CD8005      CALL    PADR
053C AF          XRA     A
053D CD8905      CALL    PBYTE
0540 7E          WCM20: MOV     A,M
0541 CD8905      CALL    PBYTE
0544 23          INX     H
0545 1D          DCR     E
0546 C24005      JNZ     WCM20
0549 AF          XRA     A
054A 92          SUB     D
054B CD8905      CALL    PBYTE
054E D1          POP     D
054F CDC105      CALL    PEOI
0552 C31005      JMP     WCM05
0555 CDA605      WCM25: CALL    PEOF
0558 C3CD02      JMP     EXIT

```

```

; *****
;      BYTE                                     UTILITY      *
;      INPUTS: D-CURRENT VALUE OF CHECKSUM                    *
;      OUTPUTS: A-HEXADECIMAL CHARACTER                      *
;                  D-UPDATED VALUE OF CHECKSUM                *
;      CALLS: CI,CNVBN                                         *
;      DESTROYS: A,D,F/F'S                                     *
;      FUNCTION: BYTE READS TWO CHARACTERS FROM THE CONSOLE AND CONVERTS *
;                  THE CHARACTERS TO ONE HEX CHARACTER.  THE A REGISTER *
;                  CONTAINS THE FINAL CHARACTER AND THE D REGISTER CONTAINS *
;                  THE UPDATED VALUE OF THE CHECKSUM.         *
; *****

```

055B	C5	BYTE:	PUSH	B
055C	CD8002		CALL	CI
055F	E67F		ANI	PRTYO
0561	4F		MOV	C, A
0562	CD9302		CALL	CO
0565	CD8A02		CALL	CVNBN
0568	07		RLC	
0569	07		RLC	
056A	07		RLC	
056B	07		RLC	
056C	47		MOV	B, A
056D	CD8002		CALL	CI
0570	E67F		ANI	PRTYO
0572	4F		MOV	C, A
0573	CD9302		CALL	CO

0576	CD8A02		CALL	CVNBN
0579	B0		ORA	B
057A	4F		MOV	C, A
057B	82		ADD	D
057C	57		MOV	D, A
057D	79		MOV	A, C
057E	C1		POP	B
057F	C9		RET	

```

;*****
;      PADR                                UTILITY      *
;      INPUTS: HL-ADDRESS TO BE PRINTED                *
;      CALLS: PBYTE                                     *
;      DESTROYS: A                                       *
;      FUNCTION: PADR PRINTS THE ADDRESS IN THE HL PAIR BY CALLING PBYTE, *
;                  THIS CAUSES THE CHECKSUM IN REGISTER D TO BE UPDATED.  *
;*****

```

0580	7C	PADR:	MOV	A, H
0581	CD8905		CALL	PBYTE
0584	7D		MOV	A, L
0585	CD8905		CALL	PBYTE
0588	C9		RET	

```

*****
;          PBYTE                                UTILITY          *
;          INPUTS: A-CHARACTER TO BE PRINTED                    *
;                   D-CURRENT VALUE OF THE CHECKSUM              *
;          OUTPUTS: D-UPDATED VALUE OF THE CHECKSUM              *
;          CALLS: PRVAL,C0                                        *
;          DESTROYS: A,F/F'S                                     *
;          FUNCTION: PBYTE CONVERTS THE HEX VALUE IN THE A REGISTER INTO 2 *
;                   ASCII CHARACTERS AND OUTPUTS THEM TO THE SERIAL PORT. *
;                   THE CHECKSUM VALUE IN THE D REGISTER IS UPDATED.      *
;*****
0589  F5      PBYTE:  PUSH      PSW
058A  0F              RRC
058B  0F              RRC
058C  0F              RRC
058D  0F              RRC
058E  CD9A03      CALL      PRVAL
0591  CD9302      CALL      C0
0594  F1          POP      PSW
0595  F5          PUSH     PSW
0596  CD9A03      CALL      PRVAL
0599  CD9302      CALL      C0
059C  F1          POP      PSW
059D  82          ADD      D
059E  57          MOV      D,A
059F  CD6102      CALL      BREAK
05A2  D0          RNC
05A3  C3CD02      JMP      EXIT
;*****
;          PEOF                                UTILITY          *
;
;          CALLS: C0,PBYTE,PADR                                *
;          DESTROYS: A,C,D,H,L,F/F'S                          *
;          FUNCTION: PEOF PRINTS THE END OF FILE RECORD CONSISTING OF A RECORD *
;                   MARK, A LOAD ADDRESS OF 0, THE RECORD TYPE, AND THE *
;                   RECORD CHECKSUM.                            *
;*****

```

05A6	0E3A	PEOF:	MVI	C, ':'
05A8	CD9302		CALL	CO
05AB	AF		XRA	A
05AC	57		MOV	D, A
05AD	CD8905		CALL	PBYTE
05B0	210000		LXI	H, OH
05B3	CD8005		CALL	PADR
05B6	3E01		MVI	A, 1H
05B8	CD8905		CALL	PBYTE
05BB	AF		XRA	A
05BC	92		SUB	D
05BD	CD8905		CALL	PBYTE
05C0	C9		RET	
;				
05C1	0E0D	PEOL:	MVI	C, CR
05C3	CD9302		CALL	CO
05C6	0E0A		MVI	C, LF
05C8	CD9302		CALL	CO
05CB	C9		RET	
;				
05CC	4F4D4D41	CMSG:	DB	'COMMANDS', CR, LF
05D0	4E44530D			
05D4	0A			
05D5	432D434F		DB	'C-COMMAND LIST', CR, LF
05D9	4D4D414E			
05DD	44204C49			
05E1	53540D0A			
05E5	442D4449		DB	'D-DISPLAY MEMORY', CR, LF
05E9	53504C41			
05ED	59204D45			
05F1	4D4F5259			
05F5	0D0A			
05F7	472D4558		DB	'G-EXECUTE PROGRAM', CR, LF
05FB	45435554			
05FF	45205052			
0603	4F475241			
0607	4D0D0A			
060A	492D494E		DB	'I-INPUT FROM PORT', CR, LF
060E	50555420			
0612	46524F4D			
0616	20504F52			
061A	540D0A			

061D	4D2D4D4F	DB	'M-MOVE MEMORY',CR,LF
0621	5645204D		
0625	454D4F52		
0629	590D0A		
062C	4F2D4F55	DB	'O-OUTPUT TO PORT',CR,LF
0630	54505554		
0634	20544F20		
0638	504F5254		
063C	0D0A		
063E	522D5245	DB	'R-READ FILE',CR,LF
0642	41442046		
0646	494C450D		
064A	0A		
064B	532D5355	DB	'S-SUBSTITUTE MEMORY',CR,LF
064F	42535449		
0653	54555445		
0657	204D454D		
065B	4F52590D		
065F	0A		
0660	572D5752	DB	'W-WRITE FILE',CR,LF
0664	49544520		
0668	46494C45		
066C	0D0A		
066E	582D4558	DB	'X-EXAMINE REGISTERS',CR,LF
0672	414D494E		
0676	45205245		
067A	47495354		
067E	4552530D		
0682	0A		
0683	FF	DB	OFFH
0684	0000	DW	0
0686	D300	TBL1:	OUT 0
0688	C9		RET
0689	DB00		IN 0
068B	C9		RET

```

382E      ;      ORG      REGS
382E      MSTAK   EQU     $
382E      00      ESAVE:  DB     0
382F      00      DSAVE:  DB     0
3830      00      CSAVE:  DB     0
3831      00      BSAVE:  DB     0
3832      00      FSAVE:  DB     0
3833      00      ASAVE:  DB     0
3834      00      LSAVE:  DB     0
3835      00      HSAVE:  DB     0
3836      0000    PSAVE:  DW     0
3838      0000    SSAVE:  DW     0
383A      00      TEMP:   DB     0
383D      ORG     BRLOC
0003      USRBR:  DS      3
38C0      ORG     RSTORG
38C0      C30000  RS1:    JMP     0

```

; JUMP TABLE FOR USER RESTARTS AND INTERRUPTS

```

38C3      C30000  RS2:    JMP     0
38C6      C30000  RS3:    JMP     0
38C9      C30000  RS4:    JMP     0
38CC      C30000  RS5:    JMP     0
38CF      C30000  RS55:   JMP     0
38D2      C30000  RS6:    JMP     0
38D5      C30000  RS65:   JMP     0
38D8      C30000  RS7:    JMP     0
38DB      C30000  RS75:   JMP     0
38DE      C30000  TRAP:   JMP     0
                        END

```

NO PROGRAM ERRORS

## SYMBOL TABLE

\* 01

A	0007	ABRD	0247	ABRDU	0250	ASAVE	3833
B	0000	BAUD	4021	BR05	0268	BR10	0276
BRCHR	001B	BREAK	0261	BRLOC	383D	BSAVE	3831
BYTE	055B	C	0001	CADR	047D	CCMD	010A
CI	0280	CMD	0027	CMSG	05CC	CNCTL	0031
CNIN	0030	CNOUT	0030	CO	0293	CONST	0031
CR	000D	CROUT	02AA	CSAVE	3830	CTAB	0493
CTCMD	00CF	CTCTL	00F8	CTHI	00FD	CTLO	00FC
CVNBN	028A	D	0002	DATA	3800	DCM05	00C7
DCM10	00CD	DCMD	00C0	DELFA	0010 *	DSAVE	382F
E	0003	ECH05	02B8	ECH10	02C6	ECH0	02AF
ERROR	02C8	ESAVE	382E	ESC	001B	EXIT	02CD
FRET	02D3	FSAVE	3832	GCM05	0101	GCM10	0107
GCMD	00EC	GETCH	02D6	GETCM	0095	GETHX	02DD
GETNM	0311	GHX05	02E3	GHX10	02FB	GNM05	0318
GNM10	032D	GNM15	033B	GNM20	0340	GNM25	034B
GNM30	034F	GO	0076	GTC03	009D *	GTC05	00AA
GTC10	00B6	H	0004	HCHAR	000F	HIL0	0356
HL05	0365	HSAVE	3835	ICM01	0153	ICMD	0142
INUST	0368	INVRT	00FF	IOTBL	38F0	KBPR0	0000 *
KBRST	0008 *	KEYPR	0800 *	L	0005	LF	000A
LSAVE	3834	M	0006	MCM05	0177	MCMD	0169
MODE	00CE	MSTAK	382E	NCMDS	000A	NEWLN	0007 *
NMOUT	0387	OC05	0124	OCMD	0113	PADR	0580
PBYTE	0589	PEOF	05A6	PEOL	05C1	PRMSG	029E
PRTYO	007F	PRVAL	039A	PSAVE	3836	PSW	0006
RBR	0002	RCM05	04CA	RCM10	04F1	RCM15	0503
RCMD	04C0	REG05	03A7	REG10	03B1	REG15	03CC
REGDS	03A4	REGS	382E	RGA05	03DB	RGA10	03E8
RGADR	03D5	RIM	0020 *	RS1	38C0	RS2	38C3
RS3	38C6	RS4	38C9	RS5	38CC	RS55	38CF
RS6	38D2	RS65	38D5	RS7	38D8	RS75	38DB
RSTOR	38C0	RSTTF	03EC	RSTU	0038 *	RTAB	049D
RTABS	0003	SCM05	0194	SCM10	019F	SCM15	01AF
SCMD	018B	SETUP	0239	SGNON	045F	SIM	0030

SOMSG	008C	SP	0006	SRET	0400	SSAVE	3838
STH05	0420	STHFO	0402 *	STHLF	040D	STLP	0065
STUP	0051	TBL1	0686	TEMP	383A	TERM	001B *
TRAP	38DE	TRDY	0001	TXBE	0004 *	UPPER	00FF *
USRBR	383D *	VALDG	042C	VALDL	0447	WARM	008C
WCM05	0510	WCM10	0525	WCM15	0528	WCM20	0540
WCM25	0555	WCMD	0509	XCM05	01D6	XCM10	01E5
XCM15	01F2	XCM20	0210	XCM25	0227	XCM27	0228
XCM30	0230	XCMD	01C4				



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